



Cisco Nexus 3600 NX-OS Programmability Guide, Release 7.x

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Preface

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- [Communications, Services, and Additional Information, on page x](#)
- [Documentation Feedback, on page x](#)
- [Related Documentation for Cisco Nexus 3600 Series Switches, on page xi](#)

Audience

This publication is for network administrators who install, configure, and maintain Cisco Nexus switches.

Document Conventions

Command descriptions use the following conventions:

Convention	Description
bold	Bold text indicates the commands and keywords that you enter literally as shown.
<i>Italic</i>	Italic text indicates arguments for which the user supplies the values.
[x]	Square brackets enclose an optional element (keyword or argument).
[x y]	Square brackets enclosing keywords or arguments separated by a vertical bar indicate an optional choice.
{x y}	Braces enclosing keywords or arguments separated by a vertical bar indicate a required choice.
[x {y z}]	Nested set of square brackets or braces indicate optional or required choices within optional or required elements. Braces and a vertical bar within square brackets indicate a required choice within an optional element.

Convention	Description
<i>variable</i>	Indicates a variable for which you supply values, in context where italics cannot be used.
string	A nonquoted set of characters. Do not use quotation marks around the string or the string will include the quotation marks.

Examples use the following conventions:

Convention	Description
<code>screen font</code>	Terminal sessions and information the switch displays are in screen font.
boldface screen font	Information you must enter is in boldface screen font.
<i>italic screen font</i>	Arguments for which you supply values are in italic screen font.
<>	Nonprinting characters, such as passwords, are in angle brackets.
[]	Default responses to system prompts are in square brackets.
!, #	An exclamation point (!) or a pound sign (#) at the beginning of a line of code indicates a comment line.

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Documentation Feedback

To provide technical feedback on this document, or to report an error or omission, please send your comments to nexus3k-docfeedback@cisco.com. We appreciate your feedback.

Related Documentation for Cisco Nexus 3600 Series Switches

The entire Cisco Nexus 3600 Series switch documentation set is available at the following URL:

<https://www.cisco.com/c/en/us/support/switches/nexus-3000-series-switches/tsd-products-support-series-home.html>



CHAPTER 1

New and Changed Information

This chapter provides release-specific information for each new and changed feature in the *Cisco Nexus 3600 Series NX-OS Programmability Guide, Release 7.x*.

- [New and Changed Information, on page 1](#)

New and Changed Information

This table summarizes the new and changed features for the *Cisco Nexus 3600 Series NX-OS Programmability Guide, Release 7.x* and where they are documented.

Table 1: New and Changed Features

Feature	Description	Changed in Release	Where Documented
XMLIN	Support for converting NX-OS CLI commands to NetConf format is documented.	7.0(3)F3(1)	Converting CLI Commands to Network Configuration Format, on page 61
XML Management Interface	Support for managing the Cisco Nexus 3600 switches with an XML-based tool through the XML-based Network Configuration Protocol (NETCONF) is documented.	7.0(3)F3(1)	XML Management Interface, on page 67
Initial release		7.0(3)F3(1)	



CHAPTER 2

Overview

- [Programmability Overview, on page 3](#)
- [Standard Network Manageability Features, on page 4](#)
- [Advanced Automation Feature, on page 4](#)
- [Programmability Support, on page 4](#)

Programmability Overview

The Cisco NX-OS software running on the Cisco Nexus 3600 Series devices is as follows:

- **Resilient**
Provides critical business-class availability.
- **Modular**
Has extensions that accommodate business needs.
- **Highly Programmatic**
Allows for rapid automation and orchestration through Application Programming Interfaces (APIs).
- **Secure**
Protects and preserves data and operations.
- **Flexible**
Integrates and enables new technologies.
- **Scalable**
Accommodates and grows with the business and its requirements.
- **Easy to use**
Reduces the amount of learning required, simplifies deployment, and provides ease of manageability.

With the Cisco NX-OS operating system, the device functions in the unified fabric mode to provide network connectivity with programmatic automation functions.

Cisco NX-OS contains Open Source Software (OSS) and commercial technologies that provide automation, orchestration, programmability, monitoring and compliance support.

For more information on Open NX-OS, see <https://developer.cisco.com/site/nx-os/>.

Standard Network Manageability Features

- SNMP (V1, V2, V3)
- Syslog
- RMON
- NETCONF
- CLI and CLI scripting

Advanced Automation Feature

The enhanced Cisco NX-OS on the device supports automation. The platform includes support for Power On Auto Provisioning (POAP).

The enhanced Cisco NX-OS on the device supports automation. The platform includes the following features that support automation:

- Power On Auto Provisioning (POAP) support
- Chef and Puppet integration
- OpenStack integration
- OpenDayLight integration and OpenFlow support

Power On Auto Provisioning Support

Power On Auto Provisioning (POAP) automates the process of installing and upgrading software images and installing configuration files on Cisco Nexus devices that are being deployed in the network for the first time. It reduces the manual tasks that are required to scale the network capacity.

When a Cisco Nexus device with the POAP feature boots and does not find the startup configuration, the device enters POAP mode. It locates a DHCP server and bootstraps itself with its interface IP address, gateway, and DNS server IP addresses. The device obtains the IP address of a TFTP server or the URL of an HTTP server and downloads a configuration script that enables the device to download and install the appropriate software image and configuration file.

Programmability Support

Cisco NX-OS on Cisco Nexus 9000 devices support several capabilities to aid programmability.

NX-API Support

Cisco NX-API allows for HTTP-based programmatic access to the Cisco Nexus 9000 platform. This support is delivered by NX-API, an open source webservice. NX-API provides the configuration and management capabilities of the Cisco NX-OS CLI with web-based APIs. The device can be set to publish the output of the API calls in XML or JSON format. This API enables rapid development on the Cisco Nexus 9000 platform.

Python Scripting

Cisco Nexus 9000 devices support Python v2.7.5 in both interactive and noninteractive (script) modes.

The Python scripting capability on the devices provides programmatic access to the switch CLI to perform various tasks, and to Power-On Auto Provisioning (POAP) and Embedded Event Manager (EEM) actions. Responses to Python calls that invoke the Cisco NX-OS CLI return text or JSON output.

The Python interpreter is included in the Cisco NX-OS software.

Bash

Cisco Nexus 9000 devices support direct Bourne-Again SHell (Bash) access. With Bash, you can access the underlying Linux system on the device and manage the system.



CHAPTER 3

Bash

- [About Bash, on page 7](#)
- [Guidelines and Limitations, on page 7](#)
- [Accessing Bash, on page 7](#)
- [Escalate Privileges to Root, on page 9](#)
- [Examples of Bash Commands, on page 10](#)
- [Managing RPMs, on page 11](#)
- [Persistently Daemonizing an SDK- or ISO-built Third Party Process, on page 14](#)
- [Persistently Starting Your Application from the Native Bash Shell, on page 14](#)
- [An Example Application in the Native Bash Shell, on page 15](#)

About Bash

In addition to the NX-OS CLI, Cisco Nexus 3600 devices support access to the Bourne-Again SHell (Bash). Bash interprets commands that you enter or commands that are read from a shell script. Using Bash enables access to the underlying Linux system on the device and to manage the system.

Guidelines and Limitations

The Bash shell has the following guidelines and limitations:

- The binaries located in the `/isan` folder are meant to be run in an environment which is setup differently from that of the shell entered from the **run bash** command. It is advisable not to use these binaries from the Bash shell as the behavior within this environment is not predictable.

Accessing Bash

In Cisco NX-OS, Bash is accessible from user accounts that are associated with the Cisco NX-OS dev-ops role or the Cisco NX-OS network-admin role.

The following example shows the authority of the dev-ops role and the network-admin role:

```
switch# show role name dev-ops
```

```
Role: dev-ops
```

```
Description: Predefined system role for devops access. This role
cannot be modified.
Vlan policy: permit (default)
Interface policy: permit (default)
Vrf policy: permit (default)
```

Rule	Perm	Type	Scope	Entity
4	permit	command		conf t ; username *
3	permit	command		bcm module *
2	permit	command		run bash *
1	permit	command		python *

```
switch# show role name network-admin
```

```
Role: network-admin
Description: Predefined network admin role has access to all commands
on the switch
```

Rule	Perm	Type	Scope	Entity
1	permit	read-write		

```
switch#
```

Bash is enabled by running the **feature bash-shell** command.

The **run bash** command loads Bash and begins at the home directory for the user.

The following examples show how to enable the Bash shell feature and how to run Bash.

```
switch# configure terminal
switch(config)# feature bash-shell
```

```
switch# run?
run          Execute/run program
run-script   Run shell scripts
```

```
switch# run bash?
bash        Linux-bash
```

```
switch# run bash
bash-4.2$ whoami
admin
bash-4.2$ pwd
/bootflash/home/admin
bash-4.2$
```



Note You can also execute Bash commands with **run bash** *command*.

For instance, you can run **whoami** using **run bash** *command*:

```
run bash whoami
```

You can also run Bash by configuring the user **shelltype**:

```
username foo shelltype bash
```

This command puts you directly into the Bash shell.

Escalate Privileges to Root

The privileges of an admin user can escalate their privileges for root access.

The following are guidelines for escalating privileges:

- Only an admin user can escalate privileges to root.
- Bash must be enabled before escalating privileges.
- Escalation to root is password protected.

NX-OS network administrator users must escalate to root to pass configuration commands to the NX-OS VSH if:

- The NX-OS user has a shell-type Bash and logs into the switch with a shell-type Bash.
- The NX-OS user logged into the switch in Bash continues to use Bash on the switch.

Run `sudo su 'vsh -c "<configuration commands>"` or `sudo bash -c 'vsh -c "<configuration commands>"`.

The example below demonstrates with network administrator user MyUser with a default shelltype Bash using **sudo** to pass configuration commands to the NX-OS:

```
ssh -l MyUser 1.2.3.4
-bash-4.2$ sudo vsh -c "configure terminal ; interface eth1/2 ; shutdown ; sleep 2 ; show interface eth1/2 brief"
```

```
-----
```

Ethernet Interface	VLAN	Type	Mode	Status	Reason	Speed	Port Ch #
Eth1/2	--	eth	routed	down	Administratively down	auto(D)	--

```
-----
```

The example below demonstrates with network administrator user MyUser with default shelltype Bash entering the NX-OS and then running Bash on the NX-OS:

```
ssh -l MyUser 1.2.3.4
-bash-4.2$ vsh -h
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```

```

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switch# run bash
bash-4.2$ vsh -c "configure terminal ; interface eth1/2 ; shutdown ; sleep 2 ; show interface
eth1/2 brief"

```

```

-----
Ethernet      VLAN      Type Mode      Status Reason                      Speed      Port
Interface                                           Ch #
-----
Eth1/2        --        eth  routed down  Administratively down      auto(D)  --

```

The following example shows how to escalate privileges to root and how to verify the escalation:

```

switch# run bash
bash-4.2$ sudo su root
bash-4.2# whoami
root
bash-4.2# exit
exit

```

Examples of Bash Commands

This section contains examples of Bash commands and output.

Displaying System Statistics

The following example displays system statistics:

```

switch# run bash
bash-4.2$ cat /proc/meminfo
<snip>
MemTotal:      16402560 kB
MemFree:       14098136 kB
Buffers:       11492 kB
Cached:        1287880 kB
SwapCached:    0 kB
Active:        1109448 kB
Inactive:      717036 kB
Active(anon):  817856 kB
Inactive(anon): 702880 kB
Active(file):  291592 kB
Inactive(file): 14156 kB
Unevictable:   0 kB
Mlocked:      0 kB
SwapTotal:    0 kB
SwapFree:     0 kB
Dirty:        32 kB
Writeback:    0 kB
AnonPages:    527088 kB
Mapped:       97832 kB
<\snip>

```

Running Bash from CLI

The following example runs **ps** from Bash using **run bash** command:

```
switch# run bash ps -el
F S   UID   PID  PPID  C  PRI  NI ADDR SZ WCHAN  TTY          TIME CMD
4 S   0     1    0  0  80   0 -   528 poll_s ?           00:00:03 init
1 S   0     2    0  0  80   0 -    0 kthrea ?           00:00:00 kthreadd
1 S   0     3    2  0  80   0 -    0 run_ks ?          00:00:56 ksoftirqd/0
1 S   0     6    2  0 -40  - -    0 cpu_st ?          00:00:00 migration/0
1 S   0     7    2  0 -40  - -    0 watchd ?          00:00:00 watchdog/0
1 S   0     8    2  0 -40  - -    0 cpu_st ?          00:00:00 migration/1
1 S   0     9    2  0  80   0 -    0 worker ?          00:00:00 kworker/1:0
1 S   0    10    2  0  80   0 -    0 run_ks ?          00:00:00 ksoftirqd/1
```

Running Python from Bash

The following example shows how to load Python and configure a switch using Python objects:

```
switch# run bash
bash-4.2$ python
Python 2.7.5 (default, Oct 8 2013, 23:59:43)
[GCC 4.7.2] on linux2
Type "help", "copyright", "credits" or "license" for more information.
>>> from cisco import *
>>> from cisco.vrf import *
>>> from cisco.interface import *
>>> vrfobj=VRF('myvrf')
>>> vrfobj.get_name()
'myvrf'
>>> vrfobj.add_interface('Ethernet1/3')
True
>>> intf=Interface('Ethernet1/3')
>>> print intf.config()

!Command: show running-config interface Ethernet1/3
!Time: Mon Nov 4 13:17:56 2013

version 6.1(2)I2(1)

interface Ethernet1/3
  vrf member myvrf

>>>
```

Managing RPMs

Installing RPMs from Bash

Procedure

	Command or Action	Purpose
Step 1	<code>sudo yum installed grep platform</code>	Displays a list of the NX-OS feature RPMs installed on the switch.

	Command or Action	Purpose
Step 2	<code>sudo yum list available</code>	Displays a list of the available RPMs.
Step 3	<code>sudo yum -y install rpm</code>	Installs an available RPM.

Example

The following is an example of installing the **bfd** RPM:

```
bash-4.2$ sudo yum list installed | grep n3600
base-files.n3600                3.0.14-r74.2                installed
bfd.lib32_n3600                1.0.0-r0                    installed
core.lib32_n3600               1.0.0-r0                    installed
eigrp.lib32_n3600              1.0.0-r0                    installed
eth.lib32_n3600                1.0.0-r0                    installed
isis.lib32_n3600               1.0.0-r0                    installed
lacp.lib32_n3600               1.0.0-r0                    installed
linecard.lib32_n3600           1.0.0-r0                    installed
lldp.lib32_n3600               1.0.0-r0                    installed
ntp.lib32_n3600                1.0.0-r0                    installed
nxos-ssh.lib32_n3600           1.0.0-r0                    installed
ospf.lib32_n3600               1.0.0-r0                    installed
perf-cisco.n3600_gdb           3.12-r0                     installed
platform.lib32_n3600           1.0.0-r0                    installed
shadow-securetty.n3600_gdb     4.1.4.3-r1                  installed
snmp.lib32_n3600               1.0.0-r0                    installed
svi.lib32_n3600                1.0.0-r0                    installed
sysvinit-inittab.n3600_gdb     2.88dsf-r14                 installed
tacacs.lib32_n3600             1.0.0-r0                    installed
task-nxos-base.n3600_gdb       1.0-r0                      installed
tor.lib32_n3600                1.0.0-r0                    installed
vtp.lib32_n3600                1.0.0-r0                    installed
bash-4.2$ sudo yum list available
bgp.lib32_n3600                1.0.0-r0
bash-4.2$ sudo yum -y install bfd
```



Note Upon switch reload during boot up, use the **rpm** command instead of **yum** for persistent RPMs. Otherwise, RPMs initially installed using **yum bash** or **install CLI** will show **reponame** or **filename** instead of **installed**.

Upgrading RPMs

Before you begin

There must be a higher version of the RPM in the Yum repository.

Procedure

	Command or Action	Purpose
Step 1	<code>sudo yum -y upgrade rpm</code>	Upgrades an installed RPM.

Example

The following is an example of upgrading the **bfd** RPM:

```
bash-4.2$ sudo yum -y upgrade bfd
```

Downgrading an RPM

Procedure

	Command or Action	Purpose
Step 1	<code>sudo yum -y downgrade rpm</code>	Downgrades the RPM if any of the Yum repositories has a lower version of the RPM.

Example

The following example shows how to downgrade the **bfd** RPM:

```
bash-4.2$ sudo yum -y downgrade bfd
```

Erasing an RPM

**Note**

The SNMP RPM and the NTP RPM are protected and cannot be erased.

You can upgrade or downgrade these RPMs. It requires a system reload for the upgrade or downgrade to take effect.

For the list of protected rpms, see `/etc/yum/protected.d/protected_pkgs.conf`.

Procedure

	Command or Action	Purpose
Step 1	<code>sudo yum -y erase rpm</code>	Erases the RPM.

Example

The following example shows how to erase the **bfd** RPM:

```
bash-4.2$ sudo yum -y erase bfd
```

Persistently Daemonizing an SDK- or ISO-built Third Party Process

Your application should have a startup bash script that gets installed in `/etc/init.d/application_name`. This startup bash script should have the following general format (for more information on this format, see <http://linux.die.net/man/8/chkconfig>).

```
#!/bin/bash
#
# <application_name> Short description of your application
#
# chkconfig: 2345 15 85
# description: Short description of your application
#
### BEGIN INIT INFO
# Provides: <application_name>
# Required-Start: $local_fs $remote_fs $network $named
# Required-Stop: $local_fs $remote_fs $network
# Description: Short description of your application
### END INIT INFO
# See how we were called.
case "$1" in
start)
# Put your startup commands here
# Set RETVAL to 0 for success, non-0 for failure
;;
stop)
# Put your stop commands here
# Set RETVAL to 0 for success, non-0 for failure
;;
status)
# Put your status commands here
# Set RETVAL to 0 for success, non-0 for failure
;;
restart|force-reload|reload)
# Put your restart commands here
# Set RETVAL to 0 for success, non-0 for failure
;;
*)
echo $"Usage: $prog {start|stop|status|restart|force-reload}"
RETVAL=2
esac

exit $RETVAL
```

Persistently Starting Your Application from the Native Bash Shell

Procedure

-
- Step 1** Install your application startup bash script that you created above into `/etc/init.d/application_name`
 - Step 2** Start your application with `/etc/init.d/application_name start`

- Step 3** Enter `chkconfig --add application_name`
- Step 4** Enter `chkconfig --level 3 application_name on`
- Run level 3 is the standard multi-user run level, and the level at which the switch normally runs.
- Step 5** Verify that your application is scheduled to run on level 3 by running `chkconfig --list application_name` and confirm that level 3 is set to on
- Step 6** Verify that your application is listed in `/etc/rc3.d`. You should see something like this, where there is an 'S' followed by a number, followed by your application name (tcollector in this example), and a link to your bash startup script in `../init.d/application_name`

```
bash-4.2# ls -l /etc/rc3.d/tcollector
lrwxrwxrwx 1 root root 20 Sep 25 22:56 /etc/rc3.d/S15tcollector -> ../init.d/tcollector
bash-4.2#
```

An Example Application in the Native Bash Shell

The following example demonstrates an application in the Native Bash Shell:

```
bash-4.2# cat /etc/init.d/hello.sh
#!/bin/bash

PIDFILE=/tmp/hello.pid
OUTPUTFILE=/tmp/hello

echo $$ > $PIDFILE
rm -f $OUTPUTFILE
while true
do
    echo $(date) >> $OUTPUTFILE
    echo 'Hello World' >> $OUTPUTFILE
    sleep 10
done
bash-4.2#
bash-4.2#
bash-4.2# cat /etc/init.d/hello
#!/bin/bash
#
# hello Trivial "hello world" example Third Party App
#
# chkconfig: 2345 15 85
# description: Trivial example Third Party App
#
### BEGIN INIT INFO
# Provides: hello
# Required-Start: $local_fs $remote_fs $network $named
# Required-Stop: $local_fs $remote_fs $network
# Description: Trivial example Third Party App
### END INIT INFO

PIDFILE=/tmp/hello.pid

# See how we were called.
case "$1" in
start)
    /etc/init.d/hello.sh &
```

```

    RETVAL=$?
;;
stop)
    kill -9 `cat $PIDFILE`
    RETVAL=$?
;;
status)
    ps -p `cat $PIDFILE`
    RETVAL=$?
;;
restart|force-reload|reload)
    kill -9 `cat $PIDFILE`
    /etc/init.d/hello.sh &
    RETVAL=$?
;;
*)
echo $"Usage: $prog {start|stop|status|restart|force-reload}"
RETVAL=2
esac

exit $RETVAL
bash-4.2#
bash-4.2# chkconfig --add hello
bash-4.2# chkconfig --level 3 hello on
bash-4.2# chkconfig --list hello
hello          0:off  1:off  2:on   3:on   4:on   5:on   6:off
bash-4.2# ls -al /etc/rc3.d/*hello*
lrwxrwxrwx 1 root root 15 Sep 27 18:00 /etc/rc3.d/S15hello -> ../init.d/hello
bash-4.2#
bash-4.2# reboot

```

After reload

```

bash-4.2# ps -ef | grep hello
root      8790      1  0 18:03 ?           00:00:00 /bin/bash /etc/init.d/hello.sh
root      8973     8775  0 18:04 ttyS0       00:00:00 grep hello
bash-4.2#
bash-4.2# ls -al /tmp/hello*
-rw-rw-rw- 1 root root 205 Sep 27 18:04 /tmp/hello
-rw-rw-rw- 1 root root   5 Sep 27 18:03 /tmp/hello.pid
bash-4.2# cat /tmp/hello.pid
8790
bash-4.2# cat /tmp/hello
Sun Sep 27 18:03:49 UTC 2015
Hello World
Sun Sep 27 18:03:59 UTC 2015
Hello World
Sun Sep 27 18:04:09 UTC 2015
Hello World
Sun Sep 27 18:04:19 UTC 2015
Hello World
Sun Sep 27 18:04:29 UTC 2015
Hello World
Sun Sep 27 18:04:39 UTC 2015
Hello World
bash-4.2#

```



CHAPTER 4

Python API

- [About the Python API](#) , on page 17
- [Using Python](#), on page 17

About the Python API

Python is an easy to learn, powerful programming language. It has efficient high-level data structures and a simple but effective approach to object-oriented programming. Python's elegant syntax and dynamic typing, together with its interpreted nature, make it an ideal language for scripting and rapid application development in many areas on most platforms.

The Python interpreter and the extensive standard library are freely available in source or binary form for all major platforms from the Python website:

<http://www.python.org/>

The same site also contains distributions of and pointers to many free third-party Python modules, programs and tools, and additional documentation.

The Cisco Nexus 3600 devices support Python v2.7.5 in both interactive and non-interactive (script) modes and is available in the Guest Shell.

The Python scripting capability gives programmatic access to the device's command-line interface (CLI) to perform various tasks and PowerOn Auto Provisioning (POAP) or Embedded Event Manager (EEM) actions. Python can also be accessed from the Bash shell.

The Python interpreter is available in the Cisco NX-OS software.

Using Python

This section describes how to write and execute Python scripts.

Cisco Python Package

Cisco NX-OS provides a Cisco Python package that enables access to many core network device modules, such as interfaces, VLANs, VRFs, ACLs and routes. You can display the details of the Cisco Python package by entering the **help()** command. To obtain additional information about the classes and methods in a module,

you can run the help command for a specific module. For example, `help(cisco.interface)` displays the properties of the `cisco.interface` module.

The following is an example of how to display information about the Cisco python package:

```
>>> import cisco
>>> help(cisco)
Help on package cisco:

NAME
    cisco

FILE
    /isan/python/scripts/cisco/__init__.py

PACKAGE CONTENTS
    acl
    bgp
    cisco_secret
    cisco_socket
    feature
    interface
    key
    line_parser
    md5sum
    nxcli
    ospf
    routemap
    routes
    section_parser
    ssh
    system
    tacacs
    vrf

CLASSES
    __builtin__.object
    cisco.cisco_secret.CiscoSecret
    cisco.interface.Interface
    cisco.key.Key
```

Using the CLI Command APIs

The Python programming language uses three APIs that can execute CLI commands. The APIs are available from the Python CLI module.

These APIs are listed in the following table. You need to enable the APIs with the `from cli import *` command. The arguments for these APIs are strings of CLI commands. To execute a CLI command through the Python interpreter, you enter the CLI command as an argument string of one of the following APIs:

Table 2: CLI Command APIs

API	Description
cli() Example: <pre>string = cli ("cli-command")</pre>	Returns the raw output of CLI commands, including control/special characters. Note The interactive Python interpreter prints control/special characters 'escaped'. A carriage return is printed as '\n' and gives results that might be difficult to read. The clip() API gives results that are more readable.
clid() Example: <pre>json_string = clid ("cli-command")</pre>	Returns JSON output for cli-command, if XML support exists for the command, otherwise an exception is thrown. Note This API can be useful when searching the output of show commands.
clip() Example: <pre>clip ("cli-command")</pre>	Prints the output of the CLI command directly to stdout and returns nothing to Python. Note <pre>clip ("cli-command")</pre> is equivalent to <pre>r=cli("cli-command") print r</pre>

When two or more commands are run individually, the state is not persistent from one command to subsequent commands.

In the following example, the second command fails because the state from the first command does not persist for the second command:

```
>>> cli("conf t")
>>> cli("interface eth4/1")
```

When two or more commands are run together, the state is persistent from one command to subsequent commands.

In the following example, the second command is successful because the state persists for the second and third commands:

```
>>> cli("conf t ; interface eth4/1 ; shut")
```



Note Commands are separated with ";" as shown in the example. (The ; must be surrounded with single blank characters.)

Invoking the Python Interpreter from the CLI

The following example shows how to invoke Python from the CLI:



Note The Python interpreter is designated with the ">>>" or "... " prompt.

```
switch# python
Python 2.7.5 (default, Oct 8 2013, 23:59:43)
[GCC 4.6.3] on linux2
Type "help", "copyright", "credits" or "license" for more information.
>>> from cli import *
>>> import json
>>> cli('configure terminal ; interface loopback 5 ; no shut')
''
>>> intflist=json.loads(clid('show interface brief'))
>>> i=0
>>> while i < len(intflist['TABLE_interface']['ROW_interface']):
...     intf=intflist['TABLE_interface']['ROW_interface'][i]
...     i=i+1
...     if intf['state'] == 'up':
...         print intf['interface']
...
mgmt0
Ethernet2/7
Ethernet4/7
loopback0
loopback5
>>>
```

Display Formats

The following examples show various display formats using the Python APIs:

Example 1:

```
>>> from cli import *
>>> cli("conf ; interface loopback 1")
''
>>> clip('where detail')
mode:
username:          admin
vdc:               switch
routing-context vrf: default
```

Example 2:

```
>>> from cli import *
>>> cli("conf ; interface loopback 1")
''
>>> cli('where detail')
' mode:          \n username:          admin\n vdc:
switch\n routing-context vrf: default\n'
>>>
```

Example 3:

```
>>> from cli import *
>>> cli("conf ; interface loopback 1")
```



```

''
>>> r = cli('where detail') ; print r
mode:
username:          admin
vdc:               EOR-1
routing-context vrf: default
>>>

```

Example 4:

```

>>> from cli import *
>>> import json
>>> out=json.loads(cli('show version'))
>>> for k in out.keys():
...     print "%30s = %s" % (k, out[k])
...
                                kern_uptm_secs = 6
                                kick_file_name = bootflash:///n3600-dk9.6.1.2.I1.1.bin
                                rr_service = None
                                module_id = Supervisor Module
                                kick_tmstamp = 10/21/2013 00:06:10
                                bios_cmpl_time = 08/17/2013
                                bootflash_size = 20971520
                                kickstart_ver_str = 6.1(2)I1(2) [build 6.1(2)I1(2)] [gdb]
                                kick_cmpl_time = 10/20/2013 4:00:00
                                chassis_id = Nexus3600 C9508 (8 Slot) Chassis
                                proc_board_id = SAL171211LX
                                    memory = 16077872
                                manufacturer = Cisco Systems, Inc.
                                kern_uptm_mins = 26
                                bios_ver_str = 06.14
                                    cpu_name = Intel(R) Xeon(R) CPU E5-2403
                                kern_uptm_hrs = 2
                                    rr_usecs = 816550
                                    rr_sys_ver = None
                                    rr_reason = Reset Requested by CLI command reload
                                    rr_ctime = Mon Oct 21 00:10:24 2013
                                header_str = Cisco Nexus Operating System (NX-OS) Software
TAC support: http://www.cisco.com/tac
Documents: http://www.cisco.com/en/US/products/ps9372/tsd\_products\_support\_series\_home.html
Copyright (c) 2002-2013, Cisco Systems, Inc. All rights reserved.
The copyrights to certain works contained herein are owned by
other third parties and are used and distributed under license.
Some parts of this software are covered under the GNU Public
License. A copy of the license is available at
http://www.gnu.org/licenses/gpl.html.
                                host_name = switch
                                mem_type = kB
                                kern_uptm_days = 0
>>>

```

Non-interactive Python

A Python script can run in non-interactive mode by providing the Python script name as an argument to the Python CLI command. Python scripts must be placed under the bootflash or volatile scheme. A maximum of 32 command line arguments for the Python script are allowed with the Python CLI command.

The Cisco Nexus 3600 device also supports the source CLI command for running Python scripts. The `bootflash:scripts` directory is the default script directory for the source CLI command.

The following example shows a script and how to run it:

```
switch# show file bootflash:deltaCounters.py
#!/isan/bin/python

from cli import *
import sys, time

ifName = sys.argv[1]
delay = float(sys.argv[2])
count = int(sys.argv[3])
cmd = 'show interface ' + ifName + ' counters'

out = json.loads(clid(cmd))
rxuc = int(out['TABLE_rx_counters']['ROW_rx_counters'][0]['eth_inucast'])
rxmc = int(out['TABLE_rx_counters']['ROW_rx_counters'][1]['eth_inmcast'])
rxbc = int(out['TABLE_rx_counters']['ROW_rx_counters'][1]['eth_inbcast'])
txuc = int(out['TABLE_tx_counters']['ROW_tx_counters'][0]['eth_outucast'])
txmc = int(out['TABLE_tx_counters']['ROW_tx_counters'][1]['eth_outmcast'])
txbc = int(out['TABLE_tx_counters']['ROW_tx_counters'][1]['eth_outbcast'])
print 'row rx_ucast rx_mcast rx_bcast tx_ucast tx_mcast tx_bcast'
print '=====
print '      %8d %8d %8d %8d %8d %8d' % (rxuc, rxmc, rxbc, txuc, txmc, txbc)
print '=====

i = 0
while (i < count):
    time.sleep(delay)
    out = json.loads(clid(cmd))
    rxucNew = int(out['TABLE_rx_counters']['ROW_rx_counters'][0]['eth_inucast'])
    rxmcNew = int(out['TABLE_rx_counters']['ROW_rx_counters'][1]['eth_inmcast'])
    rxbcNew = int(out['TABLE_rx_counters']['ROW_rx_counters'][1]['eth_inbcast'])
    txucNew = int(out['TABLE_tx_counters']['ROW_tx_counters'][0]['eth_outucast'])
    txmcNew = int(out['TABLE_tx_counters']['ROW_tx_counters'][1]['eth_outmcast'])
    txbcNew = int(out['TABLE_tx_counters']['ROW_tx_counters'][1]['eth_outbcast'])
    i += 1
    print '%-3d %8d %8d %8d %8d %8d %8d' % \
        (i, rxucNew - rxuc, rxmcNew - rxmc, rxbcNew - rxbc, txucNew - txuc, txmcNew - txmc,
        txbcNew - txbc)

switch# python bootflash:deltaCounters.py Ethernet1/1 1 5
row rx_ucast rx_mcast rx_bcast tx_ucast tx_mcast tx_bcast
=====
              0       791           1           0   212739           0
=====
1           0           0           0           0        26           0
2           0           0           0           0        27           0
3           0           1           0           0        54           0
4           0           1           0           0        55           0
5           0           1           0           0        81           0
switch#
```

The following example shows how a source command specifies command-line arguments. In the example, *policy-map* is an argument to the **cgrep python** script. The example also shows that a source command can follow after the pipe operator ("**|**").

```
switch# show running-config | source sys/cgrep policy-map

policy-map type network-qos nw-pfc
policy-map type network-qos no-drop-2
policy-map type network-qos wred-policy
policy-map type network-qos pause-policy
policy-map type qos foo
```

```

policy-map type qos classify
policy-map type qos cos-based
policy-map type qos no-drop-2
policy-map type qos pfc-tor-port

```

Running Scripts with Embedded Event Manager

On Cisco Nexus 3600 devices, embedded event manager (EEM) policies support Python scripts.

The following example shows how to run a Python script as an EEM action:

- An EEM applet can include a Python script with an action command.

```

switch# show running-config eem

!Command: show running-config eem
!Time: Sun May  1 14:40:07 2011

version 6.1(2)I2(1)
event manager applet a1
  event cli match "show clock"
  action 1 cli python bootflash:pydate.py
  action 2 event-default

```

- You can search for the action triggered by the event in the log file by running the **show file logflash:event_archive_1** command.

```

switch# show file logflash:event_archive_1 | last 33

eem_event_time:05/01/2011,19:40:28 event_type:cli event_id:8 slot:active(1)
vdc:1 severity:minor applets:a1
eem_param_info:command = "exshow clock"
Starting with policy a1
Python

2011-05-01 19:40:28.644891
Executing the following commands succeeded:
    python bootflash:pydate.py

PC_VSH_CMD_TLV(7679) with q

```

Python Integration with Cisco NX-OS Network Interfaces

On Cisco Nexus 3600 devices, Python is integrated with the underlying Cisco NX-OS network interfaces. You can switch from one virtual routing context to another by setting up a context through the `cisco.vrf.set_global_vrf()` API.

The following example shows how to retrieve an HTML document over the management interface of a device. You can also establish a connection to an external entity over the inband interface by switching to a desired virtual routing context.

```

switch# python
Python 2.7.5 (default, Oct  8 2013, 23:59:43)
[GCC 4.6.3] on linux2
Type "help", "copyright", "credits" or "license" for more information.
>>> import urllib2
>>> from cisco.vrf import *
>>> set_global_vrf('management')
>>> page=urllib2.urlopen('http://172.23.40.211:8000/welcome.html')

```

```

>>> print page.read()
Hello Cisco Nexus 3600

>>>
>>> import cisco
>>> help(cisco.vrf.set_global_vrf)
Help on function set_global_vrf in module cisco.vrf:

set_global_vrf(vrf)
    Sets the global vrf. Any new sockets that are created (using socket.socket)
    will automatically get set to this vrf (including sockets used by other
    python libraries).

    Arguments:
        vrf: VRF name (string) or the VRF ID (int).

    Returns: Nothing

>>>

```

Cisco NX-OS Security with Python

Cisco NX-OS resources are protected by the Cisco NX-OS Sandbox layer of software and by the CLI role-based access control (RBAC).

All users associated with a Cisco NX-OS network-admin or dev-ops role are privileged users. Users who are granted access to Python with a custom role are regarded as non-privileged users. Non-privileged users have a limited access to Cisco NX-OS resources, such as file system, guest shell, and Bash commands. Privileged users have greater access to all the resources of Cisco NX-OS.

Examples of Security and User Authority

The following example shows how a privileged user runs commands:

```

switch# python
Python 2.7.5 (default, Oct  8 2013, 23:59:43)
[GCC 4.6.3] on linux2
Type "help", "copyright", "credits" or "license" for more information.
>>> import os
>>> os.system('whoami')
admin
0
>>> f=open('/tmp/test','w')
>>> f.write('hello from python')
>>> f.close()
>>> r=open('/tmp/test','r')
>>> print r.read()
hello from python
>>> r.close()

```

The following example shows a non-privileged user being denied access:

```

switch# python
Python 2.7.5 (default, Oct  8 2013, 23:59:43)
[GCC 4.6.3] on linux2
Type "help", "copyright", "credits" or "license" for more information.
>>> import os
>>> os.system('whoami')
system(whoami): rejected!
-1
>>> f=open('/tmp/test','r')

```

```

Permission denied. Traceback (most recent call last):
  File "<stdin>", line 1, in <module>
IOError: [Errno 13] Permission denied: '/tmp/test'
>>>

```

RBAC controls CLI access based on the login user privileges. A login user's identity is given to Python that is invoked from the CLI shell or from Bash. Python passes the login user's identity to any subprocess that is invoked from Python.

The following is an example for a privileged user:

```

>>> from cli import *
>>> cli('show clock')
'11:28:53.845 AM UTC Sun May 08 2011\n'
>>> cli('configure terminal ; vrf context myvrf')
''
>>> clip('show running-config l3vm')

!Command: show running-config l3vm
!Time: Sun May 8 11:29:40 2011

version 6.1(2)I2(1)

interface Ethernet1/48
  vrf member blue

interface mgmt0
  vrf member management
vrf context blue
vrf context management
vrf context myvrf

```

The following is an example for a non-privileged user:

```

>>> from cli import *
>>> cli('show clock')
'11:18:47.482 AM UTC Sun May 08 2011\n'
>>> cli('configure terminal ; vrf context myvrf2')
Traceback (most recent call last):
  File "<stdin>", line 1, in <module>
  File "/isan/python/scripts/cli.py", line 20, in cli
    raise cmd_exec_error(msg)
errors.cmd_exec_error: '% Permission denied for the role\n\nCmd exec error.\n'

```

The following example shows an RBAC configuration:

```

switch# show user-account
user:admin
  this user account has no expiry date
  roles:network-admin
user:pyuser
  this user account has no expiry date
  roles:network-operator python-role
switch# show role name python-role

```

Example of Running Script with Scheduler

The following example shows a Python script that is running the script with the scheduler feature:

```

#!/bin/env python
from cli import *

```

```

from nxos import *
import os

switchname = cli("show switchname")
try:
    user = os.environ['USER']
except:
    user = "No user"
    pass

msg = user + " ran " + __file__ + " on : " + switchname
print msg
py_syslog(1, msg)
# Save this script in bootflash:///scripts

switch# conf t
Enter configuration commands, one per line. End with CNTL/Z.
switch(config)# feature scheduler
switch(config)# scheduler job name testplan
switch(config-job)# python bootflash:///scripts/testplan.py
switch(config-job)# exit
switch(config)# scheduler schedule name testplan
switch(config-schedule)# job name testplan
switch(config-schedule)# time start now repeat 0:0:4
Schedule starts from Mon Mar 14 16:40:03 2011
switch(config-schedule)# end
switch# term mon
2011 Mar 14 16:38:03 switch %VSHD-5-VSHD_SYSLOG_CONFIG_I: Configured from vty by admin on
10.19.68.246@pts/2
switch# show scheduler schedule
Schedule Name          : testplan
-----
User Name              : admin
Schedule Type          : Run every 0 Days 0 Hrs 4 Mins
Start Time             : Mon Mar 14 16:40:03 2011
Last Execution Time    : Yet to be executed
-----
Job Name               Last Execution Status
-----
testplan                -NA-
=====
switch#
switch# 2011 Mar 14 16:40:04 switch %USER-1-SYSTEM_MSG: No user ran
/bootflash/scripts/testplan.py on : switch - nxpython
2011 Mar 14 16:44:04 switch last message repeated 1 time
switch#

```



CHAPTER 5

iPXE

This chapter contains the following sections:

- [About iPXE, on page 27](#)
- [Netboot Requirements, on page 28](#)
- [Guidelines and Limitations, on page 28](#)
- [Boot Mode Configuration, on page 36](#)
- [Verifying the Boot Order Configuration, on page 38](#)

About iPXE

iPXE is an open source network boot firmware. iPXE is based on gPXE, which is an open-source PXE client firmware and bootloader derived from Etherboot. Standard PXE clients use TFTP to transfer data, whereas gPXE supports additional protocols.

Here is a list of additional features that iPXE provides over standard PXE:

- Boots from a web server via HTTP, iSCSI SAN, FCoE, etc.,
- Supports both IPv4 and IPv6,
- Netboot supports HTTP/TFTP, IPv4, and IPv6,
- Supports embedded scripts into the image or served by the HTTP/TFTP, etc., and
- Supports stateless address auto-configuration (SLAAC) and stateful IP auto-configuration variants for DHCPv6. iPXE supports boot URI and parameters for DHCPv6 options. This depends on IPv6 router advertisement.

In addition, we have disabled some of the existing features from iPXE for security reasons such as:

- Boot support for standard Linux image format such as bzImage+initramfs/initrd, or ISO, etc.,
- Unused network boot options such as FCoE, iSCSI SAN, Wireless, etc., and
- Loading of unsupported NBP (such as syslinux/pxelinux) because these might boot system images that are not properly code-signed.

Netboot Requirements

The primary requirements are:

- A DHCP server with proper configuration.
- A TFTP/HTTP server.
- Enough space on the device's bootflash because NX-OS downloads the image when the device is PXE booted.
- IPv4/IPv6 support—for better deployment flexibility

Guidelines and Limitations

PXE has the following configuration guidelines and limitations:

- While auto-booting through iPXE, there is a window of three seconds where you can enter **Ctrl+B** to exit out of the PXE boot. The system prompts you with the following options:

```
Please choose a bootloader shell:
1). GRUB shell
2). PXE shell
Enter your choice:
```

- HTTP image download vs. TFTP—TFTP is UDP based and it can be problematic if packet loss starts appearing. TCP is a window-based protocol and handles bandwidth sharing/losses better. As a result, TCP-based protocols support is more suitable given the sizes of the Cisco Nexus images which are over 250 Mbytes.
- iPXE only allows/boots Cisco signed NBI images. Other standard image format support is disabled for security reasons.

Notes for iPXE

DHCP server installation

DHCP is not installed in the server by default. You can verify DHCP server installation with the **service dhcpd status** command.

```
[switch etc]# service dhcpd status
dhcpd: unrecognized service /* indicates that dhcp server is not installed */
```

You can install DHCP with the **yum install dhcp** command.



Note Root credentials are required for installing the DHCP server.

```
[switch etc]# yum install dhcp
Repository base is listed more than once in the configuration
Setting up Install Process
Resolving Dependencies
--> Running transaction check
---> Package dhcp.x86_64 12:3.0.5-23.e15 set to be updated
--> Finished Dependency Resolution

Dependencies Resolved
=====

Package Arch Version Repository
Size
=====
Installing:
dhcp x86_64 12:3.0.5-23.e15 workstation 883
k

Transaction Summary
=====
Install 1 Package(s)
Upgrade 0 Package(s)

Total download size: 883 k
Is this ok [y/N]: y
Downloading Packages:
dhcp-3.0.5-23.e15.x86_64.rpm | 883 kB 00:00
Running rpm_check_debug
Running Transaction Test
Finished Transaction Test
Transaction Test Succeeded
Running Transaction
  Installing      : dhcp
1/1
Installed:
  dhcp.x86_64 12:3.0.5-23.e15

Complete!
[switch etc]#
```

Adding a configuration to the DHCP server

After the DHCP server is installed, the configuration file is located at `/etc/dhcpd.conf`.

The following is an example of the `dhcpd.conf` file.

```
-----
# Set the amount of time in seconds that a client may keep the IP address
default-lease-time 300;
max-lease-time 7200;
one-lease-per-client true;

#Indicate the preferred interface that your DHCP server listens only to that interface and
to no other . Preferred interface should be added to the DHCPDARGS variable
DHCPDARGS=eth0

#A subnet section is generated for each of the interfaces present on your Linux system
subnet 10.0.00.0 netmask 255.255.255.0 {

# The range of IP addresses the server will issue to DHCP enabled PC clients booting up on
the network
```

```

range 10.0.00.2 10.0.00.100;

#Address of the preferred interface
next-server 10.0.00.4;

#The default gateway to be used
option routers 10.0.00.254;

#The file path where the ipxe boot looks for the image
filename = "http://10.0.00.4/pxe/dummy";
# (http://10.0.00.4 points to the httpd service path mentioned in DocumentRoot variable
# at /etc/httpd/conf/httpd.conf ) .
# By default it points to "DocumentRoot "/var/www/html" (Refer the HTTP service section)

option domain-name "cisco.com";
option domain-name-servers 100.00.000.183;

host Nexus {
    hardware ethernet e4:c7:22:bd:c4:f9;
    fixed-address 10.0.00.42;
    filename = "http://10.0.00.4/ipxe/nxos-image.bin";

host Nexus {
    hardware ethernet 64:f6:9d:07:52:f7;
    fixed-address 10.0.00.8;
    filename = "tftp://100.00.000.48/nxos-image.bin";
-----

```

Managing the DHCP service



Note After installing the DHCP service, you need to initiate the service.

- Verifying the DHCP service

```
[switch etc]# service dhcpd status
dhcpd is stopped
```

- Starting the DHCP service

```
[switch etc]# service dhcpd start
Starting dhcpd: [ok]
```

- Stopping the DHCP service

```
[switch etc]# service dhcpd stop
Stopping dhcpd: [ok]
```

- Restarting the DHCP service



Note When the DHCP configuration file `/etc/dhcpd.conf` is updated, you need to restart the service.

```
[switch etc]# service dhcpd restart
Starting dhcpd: [ok]
```

Managing the HTTP server

- HTTP server installation

```
[switch conf]# yum install httpd
```

- Starting the HTTP service

```
[switch conf]# service httpd start
Starting httpd: httpd: Could not reliably determine the server's fully qualified domain
name,
using 100.00.000.127 for ServerName
[ OK ]
```

- Stopping the HTTP service

```
[switch conf]# service httpd stop
Stopping httpd: [ OK ]
```

- Restarting the HTTP service

```
[switch conf]# service httpd restart
Stopping httpd: [FAILED]
Starting httpd: httpd: Could not reliably determine the server's fully qualified domain
name,
using 100.00.000.127 for ServerName
[ OK ]
```

- Verifying the HTTP status

```
[switch conf]# service httpd status
httpd (pid 23032) is running...
```



Note The HTTP configuration file is located at `/etc/httpd/conf/httpd.conf`.

**Note**

- **DocumentRoot:** The directory out of which you will serve your documents. By default, all requests are taken from this directory, but symbolic links and aliases may be used to point to other locations.

- **DocumentRoot /var/www/html**

The DocumentRoot variable contains the path that represents the `http://<ip_add>` field in the **dhcpd.conf** file with the filename variable.

The following is an example:

```
host Nexus {
    hardware ethernet e4:c7:22:bd:c4:f9;
    fixed-address 10.0.00.42;
    filename = "http://10.0.00.4/ipxe/nxos-image.bin";
}
```

The filename path redirects to the location **/var/www/html/ipxe/nxos-image.bin**, where the ipxe bootup looks for the image .

- TFTP server installation

```
[switch conf]# yum install tftp
```

The TFTP configuration file located at **/etc/xinetd.d/tftp**.

The following is an example of a TFTP configuration file:

```
[switch xinetd.d]# cat tftp
# default: off
# description: The tftp server serves files using the trivial file transfer \
#               protocol. The tftp protocol is often used to boot diskless \
#               workstations, download configuration files to network-aware printers, \
#               and to start the installation process for some operating systems.
service tftp
{
    disable = no
    socket_type           = dgram
    protocol              = udp
    wait                 = yes
    user                 = root
    server               = /usr/sbin/in.tftpd
    server_args          = -s /tftpboot      # Indicates the tftp path
    per_source           = 11
    cps                  = 100 2
    flags                = IPv4
}
```

- Stopping the TFTP service

```
[switch xinetd.d]# chkconfig tftp off
```

- Starting the TFTP service

```
[switch xinetd.d]# chkconfig tftp on
```



Note When you change the TFTP configuration file, you need to restart the TFTP service.

```
host Nexus {
    hardware ethernet 64:f6:9d:07:52:f7;
    fixed-address 10.0.00.8;
    filename = "tftp://100.00.000.48/nxos-image.bin";
```



Note A prerequisite is that the nxos_image.bin has to be copied to /tftpboot shown in the above example TFTP path /tftpboot.

- iPXE using HTTP protocol

```
Nexus# sh int mgmt0
mgmt0 is up
admin state is up,
  Hardware: GigabitEthernet, address: e4c7.22bd.c4a6 (bia e4c7.22bd.c4a6)
  Internet Address is 10.0.00.42/24
  MTU 1500 bytes, BW 100000 Kbit, DLY 10 usec
  reliability 255/255, txload 1/255, rxload 1/255
Encapsulation ARPA, medium is broadcast
full-duplex, 100 Mb/s
Auto-Negotiation is turned on
Auto-mdix is turned off
EtherType is 0x0000
1 minute input rate 312 bits/sec, 0 packets/sec
1 minute output rate 24 bits/sec, 0 packets/sec
Rx
  5433 input packets 10 unicast packets 5368 multicast packets
  55 broadcast packets 405677 bytes
Tx
  187 output packets 9 unicast packets 175 multicast packets
  3 broadcast packets 45869 bytes
Nexus#

Nexus# ping 199.00.000.48 vrf management
PING 199.00.000.48 (199.00.000.48): 56 data bytes
64 bytes from 199.00.000.48: icmp_seq=0 ttl=61 time=82.075 ms
64 bytes from 199.00.000.48: icmp_seq=1 ttl=61 time=0.937 ms
64 bytes from 199.00.000.48: icmp_seq=2 ttl=61 time=0.861 ms
64 bytes from 199.00.000.48: icmp_seq=3 ttl=61 time=0.948 ms
64 bytes from 199.00.000.48: icmp_seq=4 ttl=61 time=0.961 ms

--- 199.00.000.48 ping statistics ---
5 packets transmitted, 5 packets received, 0.00% packet loss
round-trip min/avg/max = 0.861/17.156/82.075 ms
Nexus# conf t
Enter configuration commands, one per line. End with CNTL/Z.
Nexus(config)# no boot nxos
Nexus(config)# boot order pxe bootflash
Nexus(config)# end

Nexus# copy running-config startup-config
[#####] 100%
Copy complete, now saving to disk (please wait)...
```

```

Copy complete.
Nexus# reload
This command will reboot the system. (y/n)? [n] y

CISCO SWITCH Ver 8.32

CISCO SWITCH Ver 8.32
Memory Size (Bytes): 0x0000000080000000 + 0x00000000380000000
Relocated to memory
Time: 9/8/2017 1:3:28
Detected CISCO IOFPGA
Booting from Primary Bios
Code Signing Results: 0x0
Using Upgrade FPGA
FPGA Revision      : 0x20
FPGA ID            : 0x1168153
FPGA Date          : 0x20140317
Reset Cause Register: 0x20
Boot Ctrl Register : 0x60ff
EventLog Register1 : 0xc2004000
EventLog Register2 : 0xfbc77fff
Version 2.16.1240. Copyright (C) 2013 American Megatrends, Inc.
Board type 1
IOFPGA @ 0xe8000000
SLOT_ID @ 0x1b
Standalone chassis
check_bootmode: pxe2grub: Launch pxe
Trying to load ipxe
Loading Application:
/Vendor(429bdb26-48a6-47bd-664c-801204061400)/UnknownMedia(6)/EndEntire
iPXE initialising devices...ok

```

```

Cisco iPXE
iPXE 1.0.0+ (3cb3) -- Open Source Network Boot Firmware -- http://ipxe.org
Features: HTTP DNS TFTP NBI Menu
net6: e4:c7:22:bd:c4:a6 using dh8900cc on PCI02:00.3 (open)
[Link:up, TX:0 TXE:0 RX:0 RXE:0]
Configuring (net6 e4:c7:22:bd:c4:a6)..... ok
net0: fe80::2a0:c9ff:fe00:0/64 (inaccessible)
net1: fe80::2a0:c9ff:fe00:1/64 (inaccessible)
net2: fe80::2a0:c9ff:fe00:2/64 (inaccessible)
net3: fe80::2a0:c9ff:fe00:3/64 (inaccessible)
net4: fe80::200:ff:fe00:5/64 (inaccessible)
net5: fe80::200:ff:fe00:7/64 (inaccessible)
net6: 10.0.00.7/255.255.255.0 gw 10.0.00.254
net6: fe80::e6c7:22ff:febd:c4a5/64
net7: fe80::200:ff:fe00:0/64 (inaccessible)
Next server: 10.0.00.4
Filename: http://10.0.00.4/ipxe/nxos-image.bin
http://10.0.00.4/ipxe/nxos-image.bin... ok
http://10.0.00.4/ipxe/nxos_image.bin... 46%
Further device bootsup fine .

```

- iPXE using TFTP protocol

```

nexus# sh int mgmt0
mgmt0 is up
admin state is up,
  Hardware: GigabitEthernet, address: e4c7.22bd.c4a6 (bia e4c7.22bd.c4a6)
  Internet Address is 10.0.00.8/24
  MTU 1500 bytes, BW 100000 Kbit, DLY 10 usec
  reliability 255/255, txload 1/255, rxload 1/255
  Encapsulation ARPA, medium is broadcast

```

```

full-duplex, 100 Mb/s
Auto-Negotiation is turned on
Auto-mdix is turned off
EtherType is 0x0000
1 minute input rate 312 bits/sec, 0 packets/sec
1 minute output rate 24 bits/sec, 0 packets/sec
Rx
  5433 input packets 10 unicast packets 5368 multicast packets
  55 broadcast packets 405677 bytes
Tx
  187 output packets 9 unicast packets 175 multicast packets
  3 broadcast packets 45869 bytes
nexus#
nexus# ping 199.00.000.48 vrf management
PING 199.00.000.48 (199.00.000.48): 56 data bytes
64 bytes from 199.00.000.48: icmp_seq=0 ttl=61 time=82.075 ms
64 bytes from 199.00.000.48: icmp_seq=1 ttl=61 time=0.937 ms
64 bytes from 199.00.000.48: icmp_seq=2 ttl=61 time=0.861 ms
64 bytes from 199.00.000.48: icmp_seq=3 ttl=61 time=0.948 ms
64 bytes from 199.00.000.48: icmp_seq=4 ttl=61 time=0.961 ms

--- 199.00.000.48 ping statistics ---
5 packets transmitted, 5 packets received, 0.00% packet loss
round-trip min/avg/max = 0.861/17.156/82.075 ms

nexus# conf t
Enter configuration commands, one per line. End with CNTL/Z.
nexus(config)# no boot nxos
nexus(config)# boot order pxe bootflash
nexus(config)# end

nexus# copy running-config startup-config
[#####] 100%
Copy complete, now saving to disk (please wait)...
Copy complete.

nexus# reload
This command will reboot the system. (y/n)? [n] y

CISCO SWITCH Ver 8.32

CISCO SWITCH Ver 8.32
Memory Size (Bytes): 0x0000000080000000 + 0x00000000380000000
  Relocated to memory
Time: 9/8/2017 1:3:28
Detected CISCO IOFPGA
Booting from Primary Bios
Code Signing Results: 0x0
Using Upgrade FPGA
FPGA Revision      : 0x20
FPGA ID            : 0x1168153
FPGA Date          : 0x20140317
Reset Cause Register: 0x20
Boot Ctrl Register : 0x60ff
EventLog Register1 : 0xc2004000
EventLog Register2 : 0xfbc77fff
Version 2.16.1240. Copyright (C) 2013 American Megatrends, Inc.
Board type 1
IOFPGA @ 0xe8000000
SLOT_ID @ 0x1b
Standalone chassis
check_bootmode: pxe2grub: Launch pxe
Trying to load ipxe
Loading Application:

```

```
/Vendor(429bdb26-48a6-47bd-664c-801204061400)/UnknownMedia(6)/EndEntire
iPXE initialising devices...ok
```

```
Cisco iPXE
iPXE 1.0.0+ (3cb3) -- Open Source Network Boot Firmware -- http://ipxe.org
Features: HTTP DNS TFTP NBI Menu
net6: e4:c7:22:bd:c4:a6 using dh8900cc on PCI02:00.3 (open)
  [Link:up, TX:0 TXE:0 RX:0 RXE:0]
Configuring (net6 e4:c7:22:bd:c4:a6)..... ok
net0: fe80::2a0:c9ff:fe00:0/64 (inaccessible)
net1: fe80::2a0:c9ff:fe00:1/64 (inaccessible)
net2: fe80::2a0:c9ff:fe00:2/64 (inaccessible)
net3: fe80::2a0:c9ff:fe00:3/64 (inaccessible)
net4: fe80::200:ff:fe00:5/64 (inaccessible)
net5: fe80::200:ff:fe00:7/64 (inaccessible)
net6: 10.0.00.7/255.255.255.0 gw 10.0.00.254
net6: fe80::e6c7:22ff:febd:c4a5/64
net7: fe80::200:ff:fe00:0/64 (inaccessible)
Next server: 10.0.00.4
filename: tftp://199.00.000.48/nxos-image.bin
tftp://199.00.000.48/nxos-image.bin... ok
tftp://199.00.000.48/nxos_image.bin... 26%
```

```
*****
```

- Interrupting the process

Use **ctrl-B** to interrupt the process and reach the iPXE shell.

- The following is an example of booting an image residing on the PXE server using HTTP protocol:

```
iPXE> dhcp
Configuring (net6 e4:c7:22:bd:c4:a6)..... ok
iPXE>boot http://10.0.0.4/ipxe/nxos-image.bin
```

- The following is an example of booting an image residing on the PXE server using TFTP protocol:

```
iPXE> dhcp
iPXE> boot tftp://199.00.00.48/nxos-image.bin
```

Use **exit** to exit the iPXE shell.

Boot Mode Configuration

VSH CLI

```
switch# configure terminal
switch(conf)# boot order bootflash|pxe [bootflash|pxe]
switch(conf)# end
```



Note The keyword **bootflash** indicates it is Grub based booting.

For example, to do a PXE boot mode only, the configuration command is:

```
switch(conf)# boot order pxe
```

To boot Grub first, followed by PXE:

```
switch(conf)# boot order bootflash pxe
```

To boot PXE first, followed by Grub:

```
switch(conf)# boot order pxe bootflash
```

If you never use the **boot order** command, by default the boot order is Grub.



Note The following sections describe how you can toggle from Grub and iPXE.

Grub CLI

```
bootmode [-g|-p|-p2g|-g2p]
```

Keyword	Function
-g	Grub only
-p	PXE only
-p2g	PXE first, followed by Grub if PXE failed
-g2p	Grub first, followed by PXE if Grub failed

The Grub CLI is useful if you want to toggle the boot mode from the serial console without booting a full Nexus image. It can also be used to get a box out of the continuous PXE boot state.

iPXE CLI

```
bootmode [-g|--grub] [-p|--pxe] [-a|--pxe2grub] [-b|--grub2pxe]
```

Keyword	Function
-- grub	Grub only
-- pxe	PXE only
-- pxe2grub	PXE first, followed by Grub if PXE failed
-- grub2pxe	Grub first, followed by PXE if Grub failed

The iPXE CLI is useful if you wish to toggle the boot mode from the serial console without booting a full Nexus image. It can also be used to get a box out of continuous PXE boot state.

Verifying the Boot Order Configuration

To display boot order configuration information, enter the following command:

Command	Purpose
<code>show boot order</code>	Displays the current boot order from the running configuration and the boot order value on the next reload from the startup configuration.



CHAPTER 6

Kernel Stack

This chapter contains the following sections:

- [About Kernel Stack, on page 39](#)
- [Guidelines and Limitations, on page 39](#)
- [Changing the Port Range, on page 40](#)

About Kernel Stack

Kernel Stack (kstack) uses well known Linux APIs to manage the routes and front panel ports.

Open Containers, like the Guest Shell, are Linux environments that are decoupled from the host software. The customers may install or modify software within that environment without impacting the host software packages.

Kernel Stack has the following features:

Guidelines and Limitations

Using the Kernel Stack has the following guidelines and limitations:

- Guest Shell, other open containers, and the host Bash Shell use Kernel Stack (kstack).
- Open containers start in the host default namespace
 - Other network namespaces might be accessed by using the **setns** system call
 - The **nsenter** and **ip netns exec** utilities can be used to execute within the context of a different network namespace.
 - The PIDs and identify options for the **ip netns** command do not work without modification because of the file system device check. A **vrinfo** utility is provided to give the network administrator the same information.
- Open containers may read the interface state from `/proc/net/dev` or use other normal Linux utilities such as **netstat** or **ifconfig** without modification. This provides counters for packets that have initiated / terminated on the switch.

- Open containers may use **ethtool -S** to get extended statistics from the net devices. This includes packets switched through the interface.
- Open containers may run packet capture applications like **tcpdump** to capture packets initiated from or terminated on the switch.
- There is no support for networking state changes (interface creation/deletion, IP address configuration, MTU change, etc.) from the Open containers
- IPv4 and IPv6 are supported
- Raw PF_PACKET is supported
- Well-known ports (0-15000) may only be used by one stack (Netstack or kstack) at a time, regardless of the network namespace.
- There is no IP connectivity between Netstack and kstack applications. This is a host limitation which also applies to open containers.
- Open containers are not allowed to send packets directly over an Ethernet out-of-band channel (EOBC) interface to communicate with the linecards or standby Sup.
- From within an open container, direct access to the EOBC interface used for internal communication with linecards or the standby supervisor. The host bash shell should be used if this access is needed.
- The management interface (mgmt0) is represented as eth1 in the kernel netdevices.
- Use of the VXLAN overlay interface (NVE x) is not supported for applications utilizing the kernel stack. NX-OS features, including CLI commands, are able to use this interface via netstack.

Changing the Port Range

Netstack and kstack divide the port range between them. The default port ranges are as follows:

- Kstack—15001 to 58000
- Netstack—58001 to 65535



Note Within this range 63536 to 65535 are reserved for NAT.

Procedure

	Command or Action	Purpose
Step 1	<code>[no] sockets local-port-range start-port end-port</code>	This command modifies the port range for kstack. This command does not modify the Netstack range.

Example

The following example sets the kstack port range:

```
switch# sockets local-port-range 15001 25000
```

What to do next

After you have entered the command, you need to be aware of the following issues:

- You must reload the switch after entering the command.
- You must leave a minimum of 7000 ports unallocated which are used by Netstack.
- You must specify the *start-port* as 15001 or the *end-port* as 65535 to avoid holes in the port range.



CHAPTER 7

Third-Party Applications

This chapter contains the following sections:

- [About Third-Party Applications, on page 43](#)
- [Installing Signed Third-Party RPMs by Importing Keys Automatically, on page 43](#)
- [Installing Signed RPM, on page 45](#)
- [Persistent Third-Party RPMs, on page 50](#)
- [Installing RPM from VSH, on page 51](#)
- [Third-Party Applications, on page 55](#)

About Third-Party Applications

The RPMs for the Third-Party Applications are available in the repository at https://devhub.cisco.com/artifactory/open-nxos/7.0-3-12-1/x86_64. These applications are installed in the native host by using the **yum** command in the Bash shell or through the NX-OS CLI.

When you enter the **yum install rpm** command, a Cisco YUM plugin gets executed. This plugin copies the RPM to a hidden location. On switch reload, the system re-installs the RPM.

For configurations in `/etc`, a Linux process, **incron**, monitors artifacts created in the directory and copies them to a hidden location, which gets copied back to `/etc`.

Installing Signed Third-Party RPMs by Importing Keys Automatically

Setup the yum repo to point to the keys and RPM.

```
root@switch# cat /etc/yum/repos.d/puppet.repo

[puppet]

name=Puppet RPM

baseurl=file:///bootflash/puppet

enabled=1

gpgcheck=1
```

```

gpgkey=http://yum.puppetlabs.com/RPM-GPG-KEY-puppetlabs
metadata_expire=0
cost=500

bash-4.2# yum install puppet-enterprise

Loaded plugins: downloadonly, importpubkey, localrpmDB, patchaction, patching,
protect-packages

groups-repo                | 1.1 kB    00:00 ...
localdb                    | 951 B     00:00 ...
patching                   | 951 B     00:00 ...
puppet                     | 951 B     00:00 ...
thirdparty                 | 951 B     00:00 ...

Setting up Install Process

Resolving Dependencies

--> Running transaction check
---> Package puppet-enterprise.x86_64 0:3.7.1.rc2.6.g6cdc186-1.pe.nxos will be installed
--> Finished Dependency Resolution

Dependencies Resolved

=====

Package                    Arch      Version                               Repository      Size
=====
Installing:
puppet-enterprise          x86_64    3.7.1.rc2.6.g6cdc186-1.pe.nxos      puppet          14 M
Transaction Summary

=====

Install      1 Package
Total download size: 14 M
Installed size: 46 M

Is this ok [y/N]: y

Retrieving key from file:///bootflash/RPM-GPG-KEY-puppetlabs

Importing GPG key 0x4BD6EC30:

Userid: "Puppet Labs Release Key (Puppet Labs Release Key) <info@puppetlabs.com>"

```



```
From : /bootflash/RPM-GPG-KEY-puppetlabs
Is this ok [y/N]: y
Downloading Packages:
Running Transaction Check
Running Transaction Test
Transaction Test Succeeded
Running Transaction
Warning! Standby is not ready. This can cause RPM database inconsistency.
If you are certain that standby is not booting up right now, you may proceed.
Do you wish to continue?
Is this ok [y/N]: y
Warning: RPMDB altered outside of yum.
Installing : puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64          1/1
/sbin/ldconfig: /usr/lib/libboost_regex.so.1.49.0 is not a symbolic link
Installed:
puppet-enterprise.x86_64 0:3.7.1.rc2.6.g6cdc186-1.pe.nxos

Complete!
```

Installing Signed RPM

Checking a Signed RPM

Run the following command to check if a given RPM is signed or not.

```
Run, rpm -K rpm_file_name
```

Not a signed RPM

```
bash-4.2# rpm -K bgp-1.0.0-r0.lib32_n3600.rpm
bgp-1.0.0-r0.lib32_n3600.rpm: (sha1) dsa sha1 md5 OK
```

Signed RPM

```
bash-4.2#
rpm -K puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm
puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm: RSA sha1 MD5 NOT_OK
```

```
bash-4.2#
```

Signed third-party rpm requires public GPG key to be imported first before the package can be installed otherwise **yum** will throw the following error:

```
bash-4.2#
```

```
yum install puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm -q
```

```
Setting up Install Process
```

```
warning: rpmts_HdrFromFdno: Header V4 RSA/SHA1 signature: NOKEY, key ID 4bd6ec30
```

```
Cannot open: puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm. Skipping.
```

```
Error: Nothing to do
```

Installing Signed RPMs by Manually Importing Key

- Copy the GPG keys to `/etc rootfs` so that they are persisted across reboots.

```
bash-4.2# mkdir -p /etc/pki/rpm-gpg
```

```
bash-4.2# cp -f RPM-GPG-KEY-puppetlabs /etc/pki/rpm-gpg/
```

- Import the keys using the below command

```
bash-4.2# rpm --import /etc/pki/rpm-gpg/RPM-GPG-KEY-puppetlabs
```

```
bash-4.2#
```

```
bash-4.2# rpm -q gpg-pubkey
```

```
gpg-pubkey-4bd6ec30-4c37bb40
```

```
bash-4.2# rpm --import /etc/pki/rpm-gpg/RPM-GPG-KEY-puppetlabs
```

```
bash-4.2#
```

```
bash-4.2# rpm -q gpg-pubkey
```

```
gpg-pubkey-4bd6ec30-4c37bb40
```

- Install the signed RPM with *yum* command

```
bash-4.2#
```

```
yum install puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm
```

```
Loaded plugins: downloadonly, importpubkey, localrpmDB, patchaction, patching, protect-packages
```

```
groups-repo          | 1.1 kB      00:00 ...
```

```
localdb              | 951 B       00:00 ...
```

```
patching             | 951 B       00:00 ...
```

```
thirdparty           | 951 B       00:00 ...
```

Setting up Install Process

Examining puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm:
puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64

Marking puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm to be installed

Resolving Dependencies

--> Running transaction check

---> Package puppet-enterprise.x86_64 0:3.7.1.rc2.6.g6cdc186-1.pe.nxos will be installed

--> Finished Dependency ResolutionDependencies Resolved

```
=====
Package           Arch    Version                               Repository
Size
```

Installing:

```
puppet-enterprise x86_64 3.7.1.rc2.6.g6cdc186-1.pe.nxos /puppet-enterprise-
46 M                                     3.7.1.rc2.6.g6cdc186-1.
                                         pe.nxos.x86_64
```

Transaction Summary

```
=====
Install          1 Package
```

Total size: 46 M

Installed size: 46 M

Is this ok [y/N]: y

Downloading Packages:

Running Transaction Check

Running Transaction Test

Transaction Test Succeeded

Running Transaction

Installing : puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64

1/1

Installed:

puppet-enterprise.x86_64 0:3.7.1.rc2.6.g6cdc186-1.pe.nxos

```
Complete!
```

```
bash-4.2#
```

Installing Signed Third-Party RPMs by Importing Keys Automatically

Setup the yum repo to point to the keys and RPM.

```
root@switch# cat /etc/yum/repos.d/puppet.repo
```

```
[puppet]
```

```
name=Puppet RPM
```

```
baseurl=file:///bootflash/puppet
```

```
enabled=1
```

```
gpgcheck=1
```

```
gpgkey=http://yum.puppetlabs.com/RPM-GPG-KEY-puppetlabs
```

```
metadata_expire=0
```

```
cost=500
```

```
bash-4.2# yum install puppet-enterprise
```

```
Loaded plugins: downloadonly, importpubkey, localrpmDB, patchaction, patching,
protect-packages
```

```
groups-repo                | 1.1 kB    00:00 ...
localdb                    | 951 B     00:00 ...
patching                   | 951 B     00:00 ...
puppet                     | 951 B     00:00 ...
thirdparty                 | 951 B     00:00 ...
```

```
Setting up Install Process
```

```
Resolving Dependencies
```

```
--> Running transaction check
```

```
---> Package puppet-enterprise.x86_64 0:3.7.1.rc2.6.g6cdc186-1.pe.nxos will be installed
```

```
--> Finished Dependency Resolution
```

```
Dependencies Resolved
```

```
=====
```

Package	Arch	Version	Repository	Size
=====				

```
Installing:
puppet-enterprise    x86_64    3.7.1.rc2.6.g6cdc186-1.pe.nxos    puppet    14 M

Transaction Summary
=====

Install            1 Package
Total download size: 14 M
Installed size: 46 M

Is this ok [y/N]: y

Retrieving key from file:///bootflash/RPM-GPG-KEY-puppetlabs

Importing GPG key 0x4BD6EC30:

  Userid: "Puppet Labs Release Key (Puppet Labs Release Key) <info@puppetlabs.com>"
  From   : /bootflash/RPM-GPG-KEY-puppetlabs

Is this ok [y/N]: y

Downloading Packages:

Running Transaction Check
Running Transaction Test
Transaction Test Succeeded

Running Transaction

Warning! Standby is not ready. This can cause RPM database inconsistency.
If you are certain that standby is not booting up right now, you may proceed.
Do you wish to continue?

Is this ok [y/N]: y

Warning: RPMDB altered outside of yum.

Installing : puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64    1/1

/sbin/ldconfig: /usr/lib/libboost_regex.so.1.49.0 is not a symbolic link

Installed:

puppet-enterprise.x86_64 0:3.7.1.rc2.6.g6cdc186-1.pe.nxos

Complete!
```

Adding Signed RPM into Repo

Procedure

Step 1 Copy signed RPM to repo directory

Step 2 Import the corresponding key for the create repo to succeed

```
bash-4.2# ls
puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm  RPM-GPG-KEY-puppetlabs
bash-4.2#
bash-4.2# rpm --import RPM-GPG-KEY-puppetlabs
bash-4.2# createrepo .
1/1 - puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm
Saving Primary metadata
Saving file lists metadata
Saving other metadata
bash-4.2#
```

Without importing keys

```
bash-4.2# ls
puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm  RPM-GPG-KEY-puppetlabs
bash-4.2#
bash-4.2# createrepo .
warning: rpmts_HdrFromFdno: Header V4 RSA/SHA1 signature: NOKEY, key ID 4bd6ec30

Error opening package - puppet-enterprise-3.7.1.rc2.6.g6cdc186-1.pe.nxos.x86_64.rpm

Saving Primary metadata
Saving file lists metadata
Saving other metadata
```

Step 3 Create repo config file under `/etc/yum/repos.d` pointing to this repo

```
bash-4.2# cat /etc/yum/repos.d/puppet.repo
[puppet]
name=Puppet RPM
baseurl=file:///bootflash/puppet
enabled=1
gpgcheck=1
gpgkey=file:///bootflash/puppet/RPM-GPG-KEY-puppetlabs
#gpgkey=http://yum.puppetlabs.com/RPM-GPG-KEY-puppetlabs
metadata_expire=0
cost=500

bash-4.2# yum list available puppet-enterprise -q
Available Packages
puppet-enterprise.x86_64          3.7.1.rc2.6.g6cdc186-1.pe.nxos
                                puppet
bash-4.2#
```

Persistent Third-Party RPMs

The following is the logic behind persistent third-party RPMs:

- A local **yum** repository is dedicated to persistent third-party RPMs. The `/etc/yum/repos.d/thirdparty.repo` points to `/bootflash/.rpmstore/thirdparty`.
- Whenever you enter the `yum install third-party.rpm` command, a copy of the RPM is saved in `//bootflash/.rpmstore/thirdparty`.
- During a reboot, all the RPMs in the third-party repository are reinstalled on the switch.
- Any change in the `/etc` configuration files persists under `/bootflash/.rpmstore/config/etc` and they are replayed during boot on `/etc`.
- Any script created in the `/etc` directory persists across reloads. For example, a third-party service script created under `/etc/init.d/` brings up the apps during reload.

Installing RPM from VSH

Package Addition

NX-OS feature RPMs can also be installed by using the VSH CLIs.

Procedure

	Command or Action	Purpose
Step 1	<code>show install packages</code>	Displays the packages and versions that already exist.
Step 2	<code>install add ?</code>	Determine supported URIs.
Step 3	<code>install add rpm-packagename</code>	The <code>install add</code> command copies the package file to a local storage device or network server.

Example

The following example shows how to activate the Chef RPM:

```
switch# show install packages
switch# install add ?
WORD          Package name
bootflash:    Enter package uri
ftp:          Enter package uri
http:         Enter package uri
modflash:     Enter package uri
scp:          Enter package uri
sftp:         Enter package uri
tftp:         Enter package uri
usb1:         Enter package uri
usb2:         Enter package uri
volatile:     Enter package uri
switch# install add
bootflash:chef-12.0.0alpha.2+20150319234423.git.1608.b6eb10f-1.e15.x86_64.rpm
[#####] 100%
```

```
Install operation 314 completed successfully at Thu Aug 6 12:58:22 2015
```

What to do next

When you are ready to activate the package, go to [Package Activation](#).



Note Adding and activating an RPM package can be accomplished in a single command:

```
switch#
install add bootflash:chef-12.0.0alpha.2+20150319234423.git.1608.b6eb10f-1.e15.x86_64.rpm
activate
```

Package Activation

Before you begin

The RPM has to have been previously added.

Procedure

	Command or Action	Purpose
Step 1	<code>show install inactive</code>	Displays the list of packages that were added and not activated.
Step 2	<code>install activate rpm-packagename</code>	Activates the package.

Example

The following example shows how to activate a package:

```
switch# show install inactive
Boot image:
  NXOS Image: bootflash:///yumcli6.bin

Inactive Packages:
  sysinfo-1.0.0-7.0.3.x86_64
Loaded plugins: downloadonly, importpubkey, localrpmDB, patchaction, patching,
               : protect-packages
Available Packages
chef.x86_64          12.0.0alpha.2+20150319234423.git.1608.b6eb10f-1.e15  thirdparty
eigrp.lib32_n3600  1.0.0-r0                                           groups-rep
o
sysinfo.x86_64     1.0.0-7.0.3                                       patching
switch# install activate chef-12.0-1.e15.x86_64.rpm
[#####] 100%
Install operation completed successfully at Thu Aug 6 12:46:53 2015
```


Deactivating Packages

Procedure

	Command or Action	Purpose
Step 1	<code>install deactivate <i>package-name</i></code>	Deactivates the RPM package.

Example

The following example shows how to deactivate the Chef RPM package:

```
switch# install deactivate chef
```

Removing Packages

Before you begin

Deactivate the package before removing it. Only deactivated RPM packages can be removed.

Procedure

	Command or Action	Purpose
Step 1	<code>install remove <i>package-name</i></code>	Removes the RPM package.

Example

The following example shows how to remove the Chef RPM package:

```
switch# install remove chef-12.0-1.e15.x86_64.rpm
```

Displaying Installed Packages

Procedure

	Command or Action	Purpose
Step 1	<code>show install packages</code>	Displays a list of the installed packages.

Example

The following example shows how to display a list of the installed packages:

```
switch# show install packages
```

Displaying Detail Logs

Procedure

	Command or Action	Purpose
Step 1	<code>show tech-support install</code>	Displays the detail logs.

Example

The following example shows how to display the detail logs:

```
switch# show tech-support install
```

Upgrading a Package

Procedure

	Command or Action	Purpose
Step 1	<code>install add <i>package-name</i> activate upgrade</code>	Upgrade a package.

Example

The following example show how to upgrade a package:

```
switch# install add bootflash:bgp-1.0.1-r0.lib32_n3600.rpm activate ?
downgrade Downgrade package
forced Non-interactive
upgrade Upgrade package
switch# install add bootflash:bgp-1.0.1-r0.lib32_n3600.rpm activate upgrade
[#####] 100%
Install operation completed successfully at Thu Aug 6 12:46:53 2015
```

Downgrading a Package

Procedure

	Command or Action	Purpose
Step 1	<code>install add <i>package-name</i> activate downgrade</code>	Downgrade a package.

Example

The following example shows how to downgrade a package:

```
switch# install add bootflash:bgp-1.0.1-r0.lib32_n3600.rpm activate ?
downgrade Downgrade package
```

```
forced      Non-interactive
upgrade     Upgrade package
switch# install add bootflash:bgp-1.0.1-r0.lib32_n3600.rpm activate downgrade
[#####] 100%
Install operation completed successfully at Thu Aug  6 12:46:53 2015
```

Third-Party Applications

NX-OS

For more information about NX-API REST API object model specifications, see <https://developer.cisco.com/media/dme/index.html>

collectd

collectd is a daemon that periodically collects system performance statistics and provides multiple means to store the values, such as RRD files. Those statistics can then be used to find current performance bottlenecks (i.e. performance analysis) and predict future system load (that is, capacity planning).

For additional information, see <https://collectd.org>.

Ganglia

Ganglia is a scalable distributed monitoring system for high-performance computing systems such as clusters and grids. It is based on a hierarchical design targeted at federations of clusters. It leverages widely used technologies such as XML for data representation, XDR for compact, portable data transport, and RRDtool for data storage and visualization. It uses engineered data structures and algorithms to achieve very low per-node overheads and high concurrency. The implementation is robust, has been ported to an extensive set of operating systems and processor architectures, and is currently in use on thousands of clusters around the world. It has been used to link clusters across university campuses and around the world and can scale to handle clusters with 2000 nodes.

For additional information, see <http://ganglia.info>.

Iperf

Iperf was developed by NLANR/DAST to measure maximum TCP and UDP bandwidth performance. Iperf allows the tuning of various parameters and UDP characteristics. Iperf reports bandwidth, delay jitter, datagram loss.

For additional information, see <http://sourceforge.net/projects/iperf/> or <http://iperf.sourceforge.net>.

LLDP

The link layer discover protocol (LLDP) is an industry standard protocol designed to supplant proprietary link layer protocols such as EDP or CDP. The goal of LLDP is to provide an inter-vendor compatible mechanism to deliver link layer notifications to adjacent network devices.

For more information, see <https://vincentbernat.github.io/lldpd/index.html>.

Nagios

Nagios is open source software that monitors network services (through ICMP, SNMP, SSH, FTP, HTTP etc), host resources (CPU load, disk usage, system logs, etc.), and alert services for servers, switches, applications, and services through the Nagios remote plugin executor (NRPE) and through SSH or SSL tunnels.

For more information, see <https://www.nagios.org/>.

OpenSSH

OpenSSH is an open-source version of the SSH connectivity tools that encrypts all traffic (including passwords) to effectively eliminate eavesdropping, connection hijacking, and other attacks. OpenSSH provides secure tunneling capabilities and several authentication methods, and supports all SSH protocol versions.

For more information, see <http://www.openssh.com>.

Quagga

Quagga is a network routing software suite that implements various routing protocols. Quagga daemons are configured through a network accessible CLI called a "vty".



Note Only Quagga BGP has been validated.

For more information, see <http://www.nongnu.org/quagga/>.

Splunk

Splunk is a web based data collection, analysis, and monitoring tool that has a search, visualization and pre-packaged content for use-cases. The raw data is sent to the Splunk server using the Splunk Universal Forwarder. Universal Forwarders provide reliable, secure data collection from remote sources and forward that data into the Splunk Enterprise for indexing and consolidation. They can scale to tens of thousands of remote systems, collecting terabytes of data with minimal impact on performance.

For additional information, see http://www.splunk.com/en_us/download/universal-forwarder.html.

tcollector

tcollector is a client-side process that gathers data from local collectors and pushes the data to Open Time Series Database (OpenTSDB).

tcollector has the following features:

- Runs data collectors and collates the data,
- Manages connections to the time series database (TSD),
- Eliminates the need to embed TSD code in collectors,

- De-duplicates repeated values, and
- Handles wire protocol work.

For additional information, see http://opentsdb.net/docs/build/html/user_guide/utilities/tcollector.html.

tcpdump

Tcpdump is a CLI application that prints out a description of the contents of packets on a network interface that match the boolean expression; the description is preceded by a time stamp, printed, by default, as hours, minutes, seconds, and fractions of a second since midnight. It can also be run with the `-w` flag, which causes it to save the packet data to a file for later analysis, and/or with the `-r` flag, which causes it to read from a saved packet file rather than to read packets from a network interface. It can also be run with the `-V` flag, which causes it to read a list of saved packet files. In all cases, only packets that match expression will be processed by tcpdump.

For more information, see <http://www.tcpdump.org/manpages/tcpdump.1.html>.

Tshark

TShark is a network protocol analyzer on the CLI. It lets you capture packet data from a live network, or read packets from a previously saved capture file. You can either print a decoded form of those packets to the standard output or write the packets to a file. TShark's native capture file format is the pcap format, which is also the format used by **tcpdump** and various other tools. Tshark can be used within the Guest Shell 2.1 after removing the `cap_net_admin` file capability.

```
setcap
cap_net_raw=ep /sbin/dumppcap
```



Note This command must be run within the Guest Shell.

For more information, see <https://www.wireshark.org/docs/man-pages/tshark.html>.



CHAPTER 8

NX-API REST

- [About NX-API REST, on page 59](#)

About NX-API REST

NX-API REST

On Cisco Nexus devices, configuration is performed using command-line interfaces (CLIs) that run only on the device. NX-API REST improves the accessibility of the Nexus configuration by providing HTTP/HTTPS APIs that:

- Make specific CLIs available outside of the switch.
- Enable configurations that would require issuing many CLI commands by combining configuration actions in relatively few HTTP/HTTPS operations.

NX-API REST supports **show** commands, basic and advanced switch configurations, and Linux Bash.

NX-API REST uses HTTP/HTTPS as its transport. CLIs are encoded into the HTTP/HTTPS POST body. The NX-API REST backend uses the Nginx HTTP server. The Nginx process, and all of its children processes, are under Linux cgroup protection where the CPU and memory usage is capped. If the Nginx resource usage exceeds the cgroup limitations, the Nginx process is restarted and restored.

For more information about the NX-API REST SDK, see <https://developer.cisco.com/site/nx-api/documents/n3k-n9k-api-ref/>.



CHAPTER 9

Converting CLI Commands to Network Configuration Format

- [Information About XMLIN, on page 61](#)
- [Licensing Requirements for XMLIN, on page 61](#)
- [Installing and Using the XMLIN Tool, on page 62](#)
- [Converting Show Command Output to XML, on page 62](#)
- [Configuration Examples for XMLIN, on page 63](#)

Information About XMLIN

The XMLIN tool converts CLI commands to the Network Configuration (NETCONF) protocol format. NETCONF is a network management protocol that provides mechanisms to install, manipulate, and delete the configuration of network devices. It uses XML-based encoding for configuration data and protocol messages. The NX-OS implementation of the NETCONF protocol supports the following protocol operations: `<get>`, `<edit-config>`, `<close-session>`, `<kill-session>`, and `<exec-command>`.

The XMLIN tool converts show, EXEC, and configuration commands to corresponding NETCONF `<get>`, `<exec-command>`, and `<edit-config>` requests. You can enter multiple configuration commands into a single NETCONF `<edit-config>` instance.

The XMLIN tool also converts the output of show commands to XML format.

Licensing Requirements for XMLIN

Table 3: XMLIN Licensing Requirements

Product	License Requirement
Cisco NX-OS	XMLIN requires no license. Any feature not included in a license package is bundled with the Cisco NX-OS system images and is provided at no extra charge to you. For a complete explanation of the Cisco NX-OS licensing scheme, see the <i>Cisco NX-OS Licensing Guide</i> .

Installing and Using the XMLIN Tool

You can install the XMLIN tool and then use it to convert configuration commands to NETCONF format.

Before you begin

The XMLIN tool can generate NETCONF instances of commands even if the corresponding feature sets or required hardware capabilities are not available on the device. But, you might still need to install some feature sets before entering the **xmlin** command.

Procedure

	Command or Action	Purpose
Step 1	switch# xmlin	
Step 2	switch(xmlin)# configure terminal	Enters global configuration mode.
Step 3	Configuration commands	Converts configuration commands to NETCONF format.
Step 4	(Optional) switch(config)(xmlin)# end	Generates the corresponding <edit-config> request. Note You must enter the end command to finish the current XML configuration before you generate an XML instance for a show command.
Step 5	(Optional) switch(config-if-verify)(xmlin)# show commands	Converts show commands to NETCONF format.
Step 6	(Optional) switch(config-if-verify)(xmlin)# exit	Returns to EXEC mode.

Converting Show Command Output to XML

You can convert the output of show commands to XML.

Before you begin

Make sure that all features for the commands you want to convert are installed and enabled on the device. Otherwise, the commands fail.

You can use the **terminal verify-only** command to verify that a feature is enabled without entering it on the device.

Make sure that all required hardware for the commands you want to convert are present on the device. Otherwise, the commands fail.

Make sure that the XMLIN tool is installed.

Procedure

	Command or Action	Purpose
Step 1	switch# <i>show-command</i> xmlin	Enters global configuration mode. Note You cannot use this command with configuration commands.

Configuration Examples for XMLIN

The following example shows how the XMLIN tool is installed on the device and used to convert a set of configuration commands to an <edit-config> instance.

```

switch# xmlin
*****
Loading the xmlin tool. Please be patient.
*****
Cisco Nexus Operating System (NX-OS) Software
TAC support: http://www.cisco.com/tac
Copyright ©) 2002-2013, Cisco Systems, Inc. All rights reserved.
The copyrights to certain works contained in this software are
owned by other third parties and used and distributed under
license. Certain components of this software are licensed under
the GNU General Public License (GPL) version 2.0 or the GNU
Lesser General Public License (LGPL) Version 2.1. A copy of each
such license is available at
http://www.opensource.org/licenses/gpl-2.0.php and
http://www.opensource.org/licenses/lgpl-2.1.php

switch(xmlin)# configure terminal
Enter configuration commands, one per line. End with CNTL/Z.
switch(config)(xmlin)# interface ethernet 2/1
% Success
switch(config-if-verify)(xmlin)# cdp enable
% Success
switch(config-if-verify)(xmlin)# end
<?xml version="1.0"?>
<nf:rpc xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:6.2.2.:configure_"
xmlns:m="http://www.cisco.com/nxos:6.2.2.:_exec"
xmlns:ml="http://www.cisco.com/nxos:6.2.2.:configure__if-eth-base" message-id="1">
  <nf:edit-config>
    <nf:target>
      <nf:running/>
    </nf:target>
    <nf:config>
      <m:configure>
        <m:terminal>
          <interface>
            <__XML_PARAM_interface>
              <__XML_value>Ethernet2/1</__XML_value>
              <ml:cdp>
                <ml:enable/>
              </ml:cdp>
            </__XML_PARAM_interface>
          </interface>
        </m:terminal>
      </m:configure>
    </nf:config>
  </nf:edit-config>
</nf:rpc>

```

```

        </nf:config>
    </nf:edit-config>
</nf:rpc>
]]>]]>

```

The following example shows how to enter the **end** command to finish the current XML configuration before you generate an XML instance for a **show** command.

```

switch(xmlin)# configure terminal
Enter configuration commands, one per line. End with CNTL/Z.
switch(config)(xmlin)# interface ethernet 2/1
switch(config-if-verify)(xmlin)# show interface ethernet 2/1
*****
Please type "end" to finish and output the current XML document before building a new one.
*****
% Command not successful

switch(config-if-verify)(xmlin)# end
<?xml version="1.0"?>
<nf:rpc xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:6.2.2.:configure_"
xmlns:m="http://www.cisco.com/nxos:6.2.2.:_exec" message-id="1">
  <nf:edit-config>
    <nf:target>
      <nf:running/>
    </nf:target>
    <nf:config>
      <m:configure>
        <m:terminal>
          <interface>
            <__XML_PARAM__interface>
              <__XML_value>Ethernet2/1</__XML_value>
            </__XML_PARAM__interface>
          </interface>
        </m:terminal>
      </m:configure>
    </nf:config>
  </nf:edit-config>
</nf:rpc>
]]>]]>

switch(xmlin)# show interface ethernet 2/1
<?xml version="1.0"?>
<nf:rpc xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:6.2.2.:if_manager" message-id="1">
  <nf:get>
    <nf:filter type="subtree">
      <show>
        <interface>
          <__XML_PARAM__ifeth>
            <__XML_value>Ethernet2/1</__XML_value>
          </__XML_PARAM__ifeth>
        </interface>
      </show>
    </nf:filter>
  </nf:get>
</nf:rpc>
]]>]]>
switch(xmlin)# exit
switch#

```

The following example shows how you can convert the output of the **show interface brief** command to XML.

```
switch# show interface brief | xmlin
<?xml version="1.0"?>
<nf:rpc xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:6.2.2.:if_manager"

message-id="1">
  <nf:get>
    <nf:filter type="subtree">
      <show>
        <interface>
          <brief/>
        </interface>
      </show>
    </nf:filter>
  </nf:get>
</nf:rpc>
]]>]]>
```




CHAPTER 10

XML Management Interface

This section contains the following topics:

- [About the XML Management Interface, on page 67](#)
- [Licensing Requirements for the XML Management Interface, on page 68](#)
- [Prerequisites to Using the XML Management Interface, on page 69](#)
- [Using the XML Management Interface, on page 69](#)
- [Information About Example XML Instances, on page 82](#)
- [Additional References, on page 88](#)

About the XML Management Interface

About the XML Management Interface

You can use the XML management interface to configure a device. The interface uses the XML-based Network Configuration Protocol (NETCONF), which allows you to manage devices and communicate over the interface with an XML management tool or program. The Cisco NX-OS implementation of NETCONF requires you to use a Secure Shell (SSH) session for communication with the device.

NETCONF is implemented with an XML Schema (XSD) that allows you to enclose device configuration elements within a remote procedure call (RPC) message. From within an RPC message, you select one of the NETCONF operations that matches the type of command that you want the device to execute. You can configure the entire set of CLI commands on the device with NETCONF. For information about using NETCONF, see the [Creating NETCONF XML Instances, on page 72](#) and [RFC 4741](#).

For more information about using NETCONF over SSH, see [RFC 4742](#).

This section includes the following topics:

- [NETCONF Layers, on page 67](#)
- [SSH xmlagent, on page 68](#)

NETCONF Layers

The following are the NETCONF layers:

Table 4: NETCONF Layers

Layer	Example
Transport protocol	SSHv2
RPC	<rpc>, <rpc-reply>
Operations	<get-config>, <edit-config>
Content	show or configuration command

The following is a description of the four NETCONF layers:

- SSH transport protocol—Provides a secure, encrypted connection between a client and the server.
- RPC tag—Introduces a configuration command from the requestor and the corresponding reply from the XML server.
- NETCONF operation tag—Indicates the type of configuration command.
- Content—Indicates the XML representation of the feature that you want to configure.

SSH xmlagent

The device software provides an SSH service that is called xmlagent that supports NETCONF over SSH Version 2.



Note

The xmlagent service is referred to as the XML server in the Cisco NX-OS software.

NETCONF over SSH starts with the exchange of a hello message between the client and the XML server. After the initial exchange, the client sends XML requests, which the server responds to with XML responses. The client and server terminate requests and responses with the character sequence >. Because this character sequence is not valid in XML, the client and the server can interpret when the messages end, which keeps communication in sync.

The XML schemas that define XML configuration instances that you can use are described in the [Creating NETCONF XML Instances, on page 72](#) section.

Licensing Requirements for the XML Management Interface

Product	Product
Cisco NX-OS	The XML management interface requires no license. Any feature not included in a license package is bundled with the Cisco NX-OS image and is provided at no extra charge to you. For a complete explanation of the Cisco NX-OS licensing scheme, see the <i>Cisco NX-OS Licensing Guide</i> .

Prerequisites to Using the XML Management Interface

The XML management interface has the following prerequisites:

- You must install SSHv2 on the client PC.
- You must install an XML management tool that supports NETCONF over SSH on the client PC.
- You must set the appropriate options for the XML server on the device.

Using the XML Management Interface

This section describes how to manually configure and use the XML management interface. Use the XML management interface with the default settings on the device.

Configuring SSH and the XML Server Options Through the CLI

By default, the SSH server is enabled on the device. If you disable SSH, you must enable it before you start an SSH session on the client PC.

You can configure XML server options to control the number of concurrent sessions and the timeout for active sessions. You can also enable XML document validation and terminate XML sessions.



Note The XML server timeout applies only to active sessions.

For more information about configuring SSH, see the Cisco NX-OS security configuration guide for your platform.

For more information about the XML commands, see the Cisco NX-OS system management configuration guide for your platform.

Procedure

	Command or Action	Purpose
Step 1	configure terminal	Enters global configuration mode.
Step 2	<code>show xml server status</code>	(Optional) Displays information about XML server settings and active XML server sessions. You can find session numbers in the command output.
Step 3	xml server validate all	Causes validation of XML documents for the specified server session.
Step 4	xml server terminate <i>session</i>	Terminates the specified XML server session.
Step 5	no feature ssh	(Optional) Disables the SSH server so that you can generate keys.

	Command or Action	Purpose
Step 6	<code>feature ssh</code>	Enables the SSH server. The default is enabled.
Step 7	<code>show ssh server</code>	(Optional) Displays the status of the SSH server.
Step 8	<code>xml server max-session <i>sessions</i></code>	Sets the number of allowed XML server sessions. The default is 8. The range is from 1 to 8.
Step 9	<code>xml server timeout <i>seconds</i></code>	Sets the number of seconds after which the XML server session is terminated. The default is 1200 seconds. The range is from 1 to 1200.
Step 10	<code>show xml server status</code>	(Optional) Displays information about the XML server settings and active XML server sessions.
Step 11	<code>copy running-config startup-config</code>	(Optional) Saves the running configuration to the startup configuration.

Example

The following example shows how to configure SSH and XML server options through CLI

```
switch# configure terminal
switch(config)# xml server validate all
switch(config)# xml server terminate 8665
switch(config)# no feature ssh
switch(config)# feature ssh server
switch(config)# xml server max-session 6
switch(config)# xml server timeout 2400
switch(config)# copy running-config startup-config
```

Starting an SSH Session

You can start an SSHv2 session on the client PC with a command similar to the following:

```
ssh2 username@ip-address -s xmlagent
```

Enter the login username, the IP address of the device, and the service to connect to. The `xmlagent` service is referred to as the XML server in the device software.



Note The SSH command syntax can differ from the SSH software on the client PC.

If you do not receive a hello message from the XML server, verify the following conditions:

- The SSH server is enabled on the device.

- The XML server max-sessions option is adequate to support the number of SSH connections to the device.
- The active XML server sessions on the device are not all in use.

Sending the Hello Message

When you start an SSH session to the XML server, the server responds immediately with a hello message that informs the client of the server's capabilities. You must advertise your capabilities to the server with a hello message before the server processes any other requests. The XML server supports only base capabilities and expects support only for the base capabilities from the client.

The following are sample hello messages from the server and the client.



Note You must end all XML documents with `]]>]]>` to support synchronization in NETCONF over SSH.

Hello Message from the server

```
<?xml version="1.0"?>
<hello xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
  <capabilities>
    <capability>urn:ietf:params:xml:ns:netconf:base:1.0</capability>
  </capabilities>
  <session-id>25241</session-id>
</hello>]]>]]>
```

Hello Message from the Client

```
<?xml version="1.0"?>
<nc:hello xmlns:nc="urn:ietf:params:xml:ns:netconf:base:1.0">
  <nc:capabilities>
    <nc:capability>urn:ietf:params:xml:ns:netconf:base:1.0</nc:capability>
  </nc:capabilities>
</nc:hello>]]>]]>
```

Obtaining the XSD Files

Procedure

- Step 1** From your browser, navigate to the Cisco software download site at the following URL:
<http://software.cisco.com/download/navigator.html>
The Download Software page opens.
- Step 2** In the Select a Product list, choose **Switches > Data Center Switches > platform > model**.
- Step 3** If you are not already logged in as a registered Cisco user, you are prompted to log in now.

- Step 4** From the Select a Software Type list, choose **NX-OS XML Schema Definition**.
- Step 5** Find the desired release and click **Download**.
- Step 6** If you are requested, follow the instructions to apply for eligibility to download strong encryption software images.
The Cisco End User License Agreement opens.
- Step 7** Click **Agree** and follow the instructions to download the file to your PC.
-

Sending an XML Document to the XML Server

To send an XML document to the XML server through an SSH session that you opened in a command shell, you can copy the XML text from an editor and paste it into the SSH session. Although typically you use an automated method to send XML documents to the XML server, you can verify the SSH connection to the XML server with this method.

Follow these guidelines for this method:

- Verify that the XML server sent the hello message immediately after you started the SSH session by looking for the hello message text in the command shell output.
- Send the client hello message before you send any XML requests. Because the XML server sends the hello response immediately, no additional response is sent after you send the client hello message.
- Always terminate the XML document with the character sequence `]]>]]>`.

Creating NETCONF XML Instances

You can create NETCONF XML instances by enclosing XML device elements within an RPC tag and NETCONF operation tags. The XML device elements are defined in feature-based XML schema definition (XSD) files, which enclose available CLI commands in an XML format.

The following are the tags that are used in the NETCONF XML request in a framework context. Tag lines are marked with the following letter codes:

- X—XML declaration
- R—RPC request tag
- N—NETCONF operation tags
- D—Device tags

NETCONF XML Framework Context

```
X <?xml version="1.0"?>
R <nc:rpc message-id="1" xmlns:nc="urn:ietf:params:xml:ns:netconf:base:1.0"
R xmlns="http://www.cisco.com/nxos:1.0:nfcli">
N <nc:get>
N <nc:filter type="subtree">
D <show>
D <xml>
D <server>
D <status/>
D </server>
D </xml>
D </show>
N </nc:filter>
```

```
N </nc:get>
R </nc:rpc>]]>]]>
```



Note You must use your own XML editor or XML management interface tool to create XML instances.

RPC Request Tag rpc

All NETCONF XML instances must begin with the RPC request tag `<rpc>`. The example *RPC Request Tag* `<rpc>` shows the `<rpc>` element with its required **message-id** attribute. The message-id attribute is replicated in the `<rpc-reply>` and can be used to correlate requests and replies. The `<rpc>` node also contains the following XML namespace declarations:

- NETCONF namespace declaration—The `<rpc>` and NETCONF tags that are defined in the "urn:ietf:params:xml:ns:netconf:base:1.0" namespace, are present in the netconf.xsd schema file.
- Device namespace declaration—Device tags encapsulated by the `<rpc>` and NETCONF tags are defined in other namespaces. Device namespaces are feature-oriented. Cisco NX-OS feature tags are defined in different namespaces. *RPC Request Tag* `<rpc>` is an example that uses the nfcli feature. It declares that the device namespace is "xmlns=http://www.cisco.com/nxos:1.0:nfcli". nfcli.xsd contains this namespace definition. For more information, see section on *Obtaining the XSD Files*.

RPC Tag Request

```
<nc:rpc message-id="315" xmlns:nc="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns=http://www.cisco.com/nxos:1.0:nfcli">
...
</nc:rpc>]]>]]>
```

Configuration Request

The following is an example of a configuration request.

```
<?xml version="1.0"?>
<nc:rpc message-id="16" xmlns:nc="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:1.0:if_manager">
  <nc:edit-config>
    <nc:target>
      <nc:running/>
    </nc:target>
    <nc:config>
      <configure>
        <__XML_MODE__exec_configure>
          <interface>
            <ethernet>
              <interface>2/30</interface>
              <__XML_MODE__if-ethernet>
                <__XML_MODE__if-eth-base>
                  <description>
                    <desc_line>Marketing Network</desc_line>
                  </description>
                </__XML_MODE__if-eth-base>
              </__XML_MODE__if-ethernet>
            </ethernet>
          </interface>
        </__XML_MODE__exec_configure>
      </configure>
    </nc:config>
  </nc:edit-config>
```

```
</nc:rpc>]]>]]>
```

__XML__ MODE tags are used internally by the NETCONF agent. Some tags are present only as children of a certain __XML__ MODE. By examining the schema file, you can find the correct mode tag that leads to the tags representing the CLI command in XML.

NETCONF Operations Tags

NETCONF provides the following configuration operations:

Table 5: NETCONF Operations in Cisco NX-OS

NETCONF Operation	Description	Example
close-session	Closes the current XML server session.	NETCONF Close Session Instance, on page 82
commit	Sets the running configuration to the current contents of the candidate configuration.	NETCONF Commit Instance - Candidate Configuration Capability, on page 87
confirmed-commit	Provides parameters to commit the configuration for a specified time. If this operation is not followed by a commit operation within the confirm-timeout period, the configuration is reverted to the state before the confirmed-commit operation.	NETCONF Confirmed-commit Instance , on page 87
copy-config	Copies the content of source configuration datastore to the target datastore.	NETCONF copy-config Instance, on page 83
delete-config	Operation not supported.	—
edit-config	Configures features in the running configuration of the device. You use this operation for configuration commands.	NETCONF edit-config Instance, on page 83 NETCONF rollback-on-error Instance , on page 87
get	Receives configuration information from the device. You use this operation for show commands. The source of the data is the running configuration.	Creating NETCONF XML Instances, on page 72
get-config	Retrieves all or part of a configuration	NETCONF get-config Instance, on page 85

NETCONF Operation	Description	Example
kill-session	Closes the specified XML server session. You cannot close your own session. See the close-session NETCONF operation.	NETCONF Kill-session Instance, on page 83
lock	Allows the client to lock the configuration system of a device.	NETCONF Lock Instance, on page 85
unlock	Releases the configuration lock that the session issued.	NETCONF unlock Instance, on page 86
validate	Checks a candidate configuration for syntactical and semantic errors before applying the configuration to the device.	NETCONF validate Capability Instance , on page 88

Device Tags

The XML device elements represent the available CLI commands in XML format. The feature-specific schema files contain the XML tags for CLI commands of that particular feature. See the [Obtaining the XSD Files, on page 71](#) section.

Using this schema, it is possible to build an XML instance. In the following examples, the relevant portions of the nfcli.xsd schema file that was used to build [Creating NETCONF XML Instances, on page 72](#) is shown.

The following example shows XML device tags.

show xml Device Tags

```
<xs:element name="show" type="show_type_Cmd_show_xml"/>
<xs:complexType name="show_type_Cmd_show_xml">
  <xs:annotation>
    <xs:documentation>to display xml agent information</xs:documentation>
  </xs:annotation>
  <xs:sequence>
    <xs:choice maxOccurs="1">
      <xs:element name="xml" minOccurs="1" type="xml_type_Cmd_show_xml"/>
      <xs:element name="debug" minOccurs="1" type="debug_type_Cmd_show_debug"/>
    </xs:choice>
  </xs:sequence>
  <xs:attribute name="xpath-filter" type="xs:string"/>
  <xs:attribute name="uses-namespace" type="nxos:bool_true"/>
</xs:complexType>
```

The following example shows the server status device tags.

server status Device Tags

```
<xs:complexType name="xml_type_Cmd_show_xml">
  <xs:annotation>
    <xs:documentation>xml agent</xs:documentation>
  </xs:annotation>
  <xs:sequence>
    <xs:element name="server" minOccurs="1" type="server_type_Cmd_show_xml"/>
  </xs:sequence>
</xs:complexType>
```

```

<xs:complexType name="server_type_Cmd_show_xml">
<xs:annotation>
<xs:documentation>xml agent server</xs:documentation>
</xs:annotation>
<xs:sequence>
<xs:choice maxOccurs="1">
<xs:element name="status" minOccurs="1" type="status_type_Cmd_show_xml"/>
<xs:element name="logging" minOccurs="1" type="logging_type_Cmd_show_logging_facility"/>
</xs:choice>
</xs:sequence>
</xs:complexType>

```

The following example shows the device tag response.

Device Tag Response

```

<xs:complexType name="status_type_Cmd_show_xml">
<xs:annotation>
<xs:documentation>display xml agent information</xs:documentation>
</xs:annotation>
<xs:sequence>
<xs:element name="__XML_OPT_Cmd_show_xml__readonly__" minOccurs="0">
<xs:complexType>
<xs:sequence>
<xs:group ref="og_Cmd_show_xml__readonly__" minOccurs="0" maxOccurs="1"/>
</xs:sequence>
</xs:complexType>
</xs:element>
</xs:sequence>
</xs:complexType>
<xs:group name="og_Cmd_show_xml__readonly__">
<xs:sequence>
<xs:element name="__readonly__" minOccurs="1" type="__readonly__type_Cmd_show_xml"/>
</xs:sequence>
</xs:group>
<xs:complexType name="__readonly__type_Cmd_show_xml">
<xs:sequence>
<xs:group ref="bg_Cmd_show_xml_operational_status" maxOccurs="1"/>
<xs:group ref="bg_Cmd_show_xml_maximum_sessions_configured" maxOccurs="1"/>
<xs:group ref="og_Cmd_show_xml_TABLE_sessions" minOccurs="0" maxOccurs="1"/>
</xs:sequence>
</xs:complexType>

```



Note “__XML_OPT_Cmd_show_xml__readonly__” is optional. This tag represents the response. For more information on responses, see the [RPC Response Tag, on page 81](#) section.

You can use the | XML option to find the tags you can use to execute a <get>. The following is an example of the | XML option.

XML Example

```

Switch#> show xml server status | xml
<?xml version="1.0" encoding="ISO-8859-1"?>
<nf:rpc-reply xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:1.0:nfcli">
<nf:data>
<show>
<xml>
<server>
<status>

```



```

<__XML__OPT_Cmd_show_xml__readonly__>
<__readonly__>
<operational_status>
<o_status>enabled</o_status>
</operational_status>
<maximum_sessions_configured>
<max_session>8</max_session>
</maximum_sessions_configured>
</__readonly__>
</__XML__OPT_Cmd_show_xml__readonly__>
</status>
</server>
</xml>
</show>
</nf:data>
</nf:rpc-reply>
]]>]]>

```

From this response, you can see that the namespace defining tag to execute operations on this component is `http://www.cisco.com/nxos:1.0:nfcli` and the `nfcli.xsd` file can be used to build requests for this feature.

You can enclose the NETCONF operation tags and the device tags within the RPC tag. The `</rpc>` end-tag is followed by the XML termination character sequence.

Extended NETCONF Operations

Cisco NX-OS supports an `<rpc>` operation named `<exec-command>`. The operation allows client applications to send CLI configuration and show commands and to receive responses to those commands as XML tags.

The following is an example of the tags that are used to configure an interface. Tag lines are marked with the following letter codes:

- X—XML declaration
- R—RPC request tag
- EO—Extended operation

Configuration CLI Commands Sent Through `<exec-command>`

```

X <?xml version="1.0"?>
R <nf:rpc xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns:nxos="http://www.cisco.com/nxos:1.0" message-id="3">
EO <nxos:exec-command>
EO <nxos:cmd>conf t ; interface ethernet 2/1 </nxos:cmd>
EO <nxos:cmd>channel-group 2000 ; no shut; </nxos:cmd>
EO </nxos:exec-command>
R </nf:rpc>]]>]]>

```

The following is the response to the operation:

Response to CLI Commands Sent Through `<exec-command>`

```

<?xml version="1.0" encoding="ISO-8859-1"?>
<nf:rpc-reply xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns:nxos="http://www.cisco.com/nxos:1.0" message-id="3">
<nf:ok/>
</nf:rpc-reply>
]]>]]>

```

The following example shows how the show CLI commands that are sent through the `<exec-command>` can be used to retrieve data.

show CLI Commands Sent Through `<exec-command>`

```
<?xml version="1.0"?>
<nf:rpc xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns:nxos="http://www.cisco.com/nxos:1.0" message-id="110">
<nxos:exec-command>
<nxos:cmd>show interface brief</nxos:cmd>
</nxos:exec-command>
</nf:rpc>]]>]]>
```

The following is the response to the operation.

Response to the show CLI commands Sent Through `<exec-command>`

```
<?xml version="1.0" encoding="ISO-8859-1"?>
<nf:rpc-reply xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns:nxos="http://www.cisco.com/nxos:1.0"
xmlns:mod="http://www.cisco.com/nxos:1.0:if_manager" message-id="110">
<nf:data>
<mod:show>
<mod:interface>
<mod: __XML_OPT_Cmd_show_interface_brief__readonly__>
<mod: __readonly__>
<mod:TABLE_interface>
<mod:ROW_interface>
<mod:interface>mgmt0</mod:interface>
<mod:state>up</mod:state>
<mod:ip_addr>172.23.152.20</mod:ip_addr>
<mod:speed>1000</mod:speed>
<mod:mtu>1500</mod:mtu>
</mod:ROW_interface>
<mod:ROW_interface>
<mod:interface>Ethernet2/1</mod:interface>
<mod:vlan>--</mod:vlan>
<mod:type>eth</mod:type>
<mod:portmode>routed</mod:portmode>
<mod:state>down</mod:state>
<mod:state_rsn_desc>Administratively down</mod:state_rsn_desc>
<mod:speed>auto</mod:speed>
<mod:ratemode>D</mod:ratemode>
</mod:ROW_interface>
</mod:TABLE_interface>
</mod: __readonly__>
</mod: __XML_OPT_Cmd_show_interface_brief__readonly__>
</mod:interface>
</mod:show>
</nf:data>
</nf:rpc-reply>
]]>]]>
```

The following table provides a detailed explanation of the operation tags:

Table 6: Tags

Tag	Description
<code><exec-command></code>	Executes a CLI command.

Tag	Description
<cmd>	Contains the CLI command. A command can be a show or configuration command. Separate multiple configuration commands by using a semicolon “;”. Multiple show commands are not supported. You can send multiple configuration commands in different <cmd> tags as part of the same request. For more information, see the Example in <i>Configuration CLI Commands Sent Through <exec-command></i> .

Replies to configuration commands that are sent through the <cmd> tag are as follows:

- <nf:ok>: All configure commands are executed successfully.
- <nf:rpc-error>: Some commands have failed. The operation stops on the first error, and the <nf:rpc-error> subtree provides more information on what configuration failed. Notice that any configuration that is executed before the failed command would have been applied to the running configuration.

The following example shows a failed configuration:

Failed Configuration

```
<?xml version="1.0"?>
<nf:rpc xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns:nxos="http://www.cisco.com/nxos:1.0" message-id="3">
<nxos:exec-command>
<nxos:cmd>configure terminal ; interface ethernet2/1 </nxos:cmd>
<nxos:cmd>ip address 1.1.1.2/24 </nxos:cmd>
<nxos:cmd>no channel-group 2000 ; no shut; </nxos:cmd>
</nxos:exec-command>
</nf:rpc>]]>]]>
<?xml version="1.0" encoding="ISO-8859-1"?>
<nf:rpc-reply xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns:nxos="http://www.cisco.com/nxos:1.0" message-id="3">
<nf:rpc-error>
<nf:error-type>application</nf:error-type>
<nf:error-tag>invalid-value</nf:error-tag>
<nf:error-severity>error</nf:error-severity>
<nf:error-message>Ethernet2/1: not part of port-channel 2000
</nf:error-message>
<nf:error-info>
<nf:bad-element>cmd</nf:bad-element>
</nf:error-info>
</nf:rpc-error>
</nf:rpc-reply>
]]>]]>
```

Because of a command execution, the interface IP address is set, but the administrative state is not modified (the no shut command is not executed). The reason the administrative state is not modified is because the no port-channel 2000 command results in an error.

The <rpc-reply> results from a show command that is sent through the <cmd> tag that contains the XML output of the show command.

You cannot combine configuration and show commands on the same <exec-command> instance. The following example shows a configuration and **show** command that are combined in the same instance.

Combination of Configuration and show Commands

```
<?xml version="1.0"?>
<nf:rpc xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns:nxos="http://www.cisco.com/nxos:1.0" message-id="110">
<nxos:exec-command>
<nxos:cmd>conf t ; interface ethernet 2/1 ; ip address 1.1.1.4/24 ; show xml
server status </nxos:cmd>
</nxos:exec-command>
</nf:rpc>]]>]]>
<?xml version="1.0" encoding="ISO-8859-1"?>
<nf:rpc-reply xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns:nxos="http://www.cisco.com/nxos:1.0" message-id="110">
<nf:rpc-error>
<nf:error-type>application</nf:error-type>
<nf:error-tag>invalid-value</nf:error-tag>
<nf:error-severity>error</nf:error-severity>
<nf:error-message>Error: cannot mix config and show in exec-command. Config cmds
before the show were executed.
Cmd:show xml server status</nf:error-message>
<nf:error-info>
<nf:bad-element>cmd</nf:bad-element>
</nf:error-info>
</nf:rpc-error>
</nf:rpc-reply>
]]>]]>
```

The show command must be sent in its own `<exec-command>` instance as shown in the following example:

Show CLI Commands Sent Through `<exec-command>`

```
<?xml version="1.0"?>
<nf:rpc xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns:nxos="http://www.cisco.com/nxos:1.0" message-id="110">
<nxos:exec-command>
<nxos:cmd>show xml server status ; show xml server status </nxos:cmd>
</nxos:exec-command>
</nf:rpc>]]>]]>
<?xml version="1.0" encoding="ISO-8859-1"?>
<nf:rpc-reply xmlns:nf="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns:nxos="http://www.cisco.com/nxos:1.0" message-id="110">
<nf:rpc-error>
<nf:error-type>application</nf:error-type>
<nf:error-tag>invalid-value</nf:error-tag>
<nf:error-severity>error</nf:error-severity>
<nf:error-message>Error: show cmds in exec-command shouldn't be followed by anything
</nf:error-message>
<nf:error-info>
<nf:bad-element>&lt;cmd&gt;</nf:bad-element>
</nf:error-info>
</nf:rpc-error>
</nf:rpc-reply>
]]>]]>
```

NETCONF Replies

For every XML request sent by the client, the XML server sends an XML response enclosed in the RPC response tag `<rpc-reply>`.

This section contains the following topics:

- [RPC Response Tag, on page 81](#)
- [Interpreting Tags Encapsulated in the Data Tag, on page 81](#)

RPC Response Tag

The following example shows the RPC response tag <rpc-reply>.

RPC Response Elements

```
<nc:rpc-reply message-id="315" xmlns:nc="urn:iETF:params:xml:ns:netconf:base:1.0"
xmlns=http://www.cisco.com/nxos:1.0:nfcli">
<ok/>
</nc:rpc-reply>]]>]]>
```

The elements <ok>, <data>, and <rpc-error> can appear in the RPC response. The following table describes the RPC response elements that can appear in the <rpc-reply> tag.

Table 7: RPC Response Elements

Element	Description
<ok>	The RPC request completed successfully. This element is used when no data is returned in the response.
<data>	The RPC request completed successfully. The data associated with the RPC request is enclosed in the <data> element.
<rpc-error>	The RPC request failed. Error information is enclosed in the <rpc-error> element.

Interpreting Tags Encapsulated in the Data Tag

The device tags encapsulated by the <data> tag contain the request followed by the response. A client application can safely ignore all tags before the <readonly> tag. The following is an example:

RPC-reply data

```
<?xml version="1.0" encoding="ISO-8859-1"?>
<nf:rpc-reply xmlns:nf="urn:iETF:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:1.0:if_manager">
<nf:data>
<show>
<interface>
<_XML_OPT_Cmd_show_interface_brief__readonly__>
<_readonly__>
<TABLE_interface>
<ROW_interface>
<interface>mgmt0</interface>
<state>up</state>
<ip_addr>xx.xx.xx.xx</ip_addr>
<speed>1000</speed>
<mtu>1500</mtu>
</ROW_interface>
<ROW_interface>
<interface>Ethernet2/1</interface>
```

```

<vlan>--</vlan>
<type>eth</type>
<portmode>routed</portmode>
<state>down</state>
<state_rsn_desc>Administratively down</state_rsn_desc>
<speed>auto</speed>
<ratemode>D</ratemode>
</ROW_interface>
</TABLE_interface>
</__readonly__>
</__XML__OPT_Cmd_show_interface_brief__readonly__>
</interface>
</show>
</nf:data>
</nf:rpc-reply>
]]>]]>

```

<__XML__OPT.*> and <__XML__BLK.*> appear in responses and are sometimes used in requests. These tags are used by the NETCONF agent and are present in responses after the <__readonly__> tag. They are necessary in requests and should be added according to the schema file to reach the XML tag that represents the CLI command.

Information About Example XML Instances

Example XML Instances

This section provides the examples of the following XML instances:

- [NETCONF Close Session Instance, on page 82](#)
- [NETCONF Kill-session Instance, on page 83](#)
- [NETCONF copy-config Instance, on page 83](#)
- [NETCONF edit-config Instance, on page 83](#)
- [NETCONF get-config Instance, on page 85](#)
- [NETCONF Lock Instance, on page 85](#)
- [NETCONF unlock Instance, on page 86](#)
- [NETCONF Commit Instance - Candidate Configuration Capability, on page 87](#)
- [NETCONF Confirmed-commit Instance , on page 87](#)
- [NETCONF rollback-on-error Instance , on page 87](#)
- [NETCONF validate Capability Instance , on page 88](#)

NETCONF Close Session Instance

The following example shows the close-session request, followed by the close-session response.

Close-session Request

```

<?xml version="1.0"?>
<nc:rpc message-id="101" xmlns:nc="urn:iETF:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:1.0">
<nc:close-session/>
</nc:rpc>]]>]]>

```

Close-session Response

```
<nc:rpc-reply xmlns:nc="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:1.0" message-id="101">
<nc:ok/>
</nc:rpc-reply>]]>]]>
```

NETCONF Kill-session Instance

The following example shows the kill-session request followed by the kill-session response.

Kill-session Request

```
<nc:rpc message-id="101" xmlns:nc="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:1.0">
<nc:kill-session>
<nc:session-id>25241</nc:session-id>
</nc:kill-session>
</nc:rpc>]]>]]>
```

Kill-session Request

```
<nc:rpc message-id="101" xmlns:nc="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:1.0">
<nc:kill-session>
<nc:session-id>25241</nc:session-id>
</nc:kill-session>
</nc:rpc>]]>]]>
```

NETCONF copy-config Instance

The following example shows the copy-config request followed by the copy-config response.

Copy-config Request

```
<rpc message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<copy-config>
<target>
<running/>
</target>
<source>
<url>https://user@example.com:passphrase/cfg/new.txt</url>
</source>
</copy-config>
</rpc>
```

Copy-config Response

```
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<ok/>
</rpc-reply>
```

NETCONF edit-config Instance

The following example shows the use of NETCONF edit-config.

Edit-config Request

```
<?xml version="1.0"?>
<nc:rpc message-id="16" xmlns:nc="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:1.0:if_manager">
<nc:edit-config>
<nc:target>
<nc:running/>
</nc:target>
<nc:config>
<configure>
<__XML__MODE__exec_configure>
<interface>
<ethernet>
<interface>2/30</interface>
<__XML__MODE_if-ethernet>
<__XML__MODE_if-eth-base>
<description>
<desc_line>Marketing Network</desc_line>
</description>
</__XML__MODE_if-eth-base>
</__XML__MODE_if-ethernet>
</ethernet>
</interface>
</__XML__MODE__exec_configure>
</configure>
</nc:config>
</nc:edit-config>
</nc:rpc>]]>]]>
```

Edit-config Response

```
<?xml version="1.0"?>
<nc:rpc-reply xmlns:nc="urn:ietf:params:xml:ns:netconf:base:1.0"
xmlns="http://www.cisco.com/nxos:1.0:if_manager" message-id="16">
<nc:ok/>
</nc:rpc-reply>]]>]]>
```

The operation attribute in edit-config identifies the point in configuration where the specified operation is performed. If the operation attribute is not specified, the configuration is merged into the existing configuration data store. Operation attribute can have the following values:

- create
- merge
- delete

The following example shows how to delete the configuration of interface Ethernet 0/0 from the running configuration.

Edit-config: Delete Operation Request

```
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<edit-config>
<target>
<running/>
</target>
<default-operation>none</default-operation>
<config xmlns:xc="urn:ietf:params:xml:ns:netconf:base:1.0">
<top xmlns="http://example.com/schema/1.2/config">
```



```

<interface xc:operation="delete">
<name>Ethernet0/0</name>
</interface>
</top>
</config>
</edit-config>
</rpc>]]>]]>

```

Response to edit-config: Delete Operation

```

<rpc-reply message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<ok/>
</rpc-reply>]]>]]>

```

NETCONF get-config Instance

The following example shows the use of NETCONF get-config.

Get-config Request to Retrieve the Entire Subtree

```

<rpc message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<get-config>
<source>
<running/>
</source>
<filter type="subtree">
<top xmlns="http://example.com/schema/1.2/config">
<users/>
</top>
</filter>
</get-config>
</rpc>]]>]]>

```

Get-config Response with Results of the Query

```

<rpc-reply message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<data>
<top xmlns="http://example.com/schema/1.2/config">
<users>
<user>
<name>root</name>
<type>superuser</type>
<full-name>Charlie Root</full-name>
<company-info>
<dept>1</dept>
<id>1</id>
</company-info>
</user>
<!-- additional <user> elements appear here... -->
</users>
</top>
</data>
</rpc-reply>]]>]]>

```

NETCONF Lock Instance

The following example shows the use of NETCONF lock operation.

The following examples show the lock request, a success response, and a response to an unsuccessful attempt.

Lock Request

```
<rpc message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<lock>
<target>
<running/>
</target>
</lock>
</rpc>]]]]>
```

Response to Successful Acquisition of Lock

```
<rpc-reply message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<ok/> <!-- lock succeeded -->
</rpc-reply>]]]]>
```

Response to Unsuccessful Attempt to Acquire the Lock

```
<rpc-reply message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<rpc-error> <!-- lock failed -->
<error-type>protocol</error-type>
<error-tag>lock-denied</error-tag>
<error-severity>error</error-severity>
<error-message>
Lock failed, lock is already held
</error-message>
<error-info>
<session-id>454</session-id>
<!-- lock is held by NETCONF session 454 -->
</error-info>
</rpc-error>
</rpc-reply>]]]]>
```

NETCONF unlock Instance

The following example shows the use of the NETCONF unlock operation.

unlock request

```
<rpc message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<unlock>
<target>
<running/>
</target>
</unlock>
</rpc>
```

response to unlock request

```
<rpc-reply message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
```

```
<ok/>
</rpc-reply>
```

NETCONF Commit Instance - Candidate Configuration Capability

The following example shows the commit operation and the commit reply:

Commit Operation

```
<rpc message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<commit/>
</rpc>
```

Commit Reply

```
<rpc-reply message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<ok/>
</rpc-reply>
```

NETCONF Confirmed-commit Instance

The following example shows the confirmed-commit operation and the confirmed-commit reply.

Confirmed Commit Request

```
<rpc message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<commit>
<confirmed/>
<confirm-timeout>120</confirm-timeout>
</commit>
</rpc>]]>]]>
```

Confirmed Commit Response

```
<rpc-reply message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<ok/>
</rpc-reply>]]>]]>
```

NETCONF rollback-on-error Instance

The following example shows the use of NETCONF rollback on error capability. The string `urn:ietf:params:netconf:capability:rollback-on-error:1.0` identifies the capability.

The following example shows how to configure rollback on error and the response to this request.

Rollback-on-error capability

```
<rpc message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<edit-config>
<target>
<running/>
```

```

</target>
<error-option>rollback-on-error</error-option>
<config>
<top xmlns="http://example.com/schema/1.2/config">
<interface>
<name>Ethernet0/0</name>
<mtu>100000</mtu>
</interface>
</top>
</config>
</edit-config>
</rpc>]]]]>

```

Rollback-on-error response

```

<rpc-reply message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<ok/>
</rpc-reply>]]]]>

```

NETCONF validate Capability Instance

The following example shows the use of the NETCONF validate capability. The string `urn:ietf:params:netconf:capability:validate:1.0` identifies the capability.

Validate request

```

xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<validate>
<source>
<candidate/>
</source>
</validate>
</rpc>]]]]>

```

Response to validate request

```

<rpc-reply message-id="101"
xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
<ok/>
</rpc-reply>]]]]>

```

Additional References

This section provides additional information that is related to implementing the XML management interface.

Standards

Standards	Title
No new or modified standards are supported by this feature. Support for existing standards has not been modified by this feature.	—

RFCs

RFCs	Title
RFC 4741	NETCONF Configuration Protocol
RFC 4742	Using the NETCONF Configuration Protocol over Secure Shell (SSH)

